

PHRC

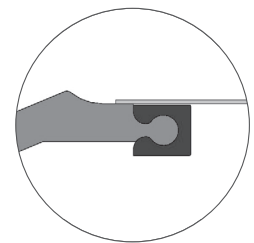
series



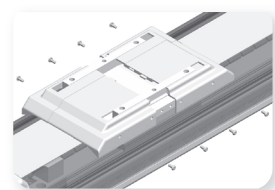
30 · 40 · 50 Mini 타입 등 다양한 제품군

투시형 커버 (폴리 · 모터)

압출 자석 적용으로 높은 내구성



2분할 SLIDE COVER로 교체가 용이



PHRC Series

주문형식 Order Information



① 형식 Type

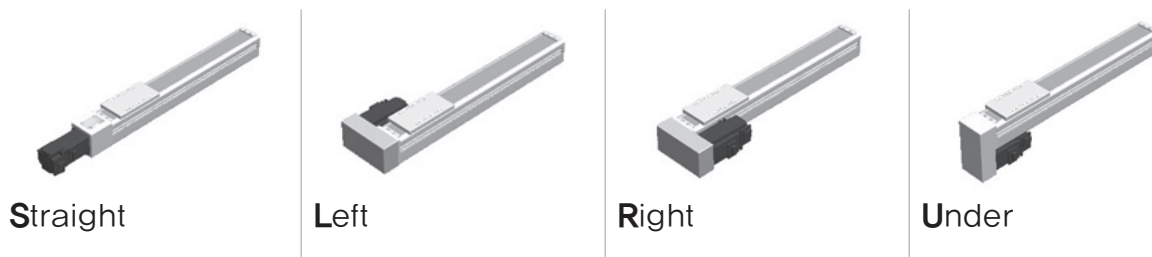
C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

30 30mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	100	200	300	400	500
L : 0802-C7						

⑤ 모터용량 Motor capacity

5 50W **10** 100W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 100mm/s

※ 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

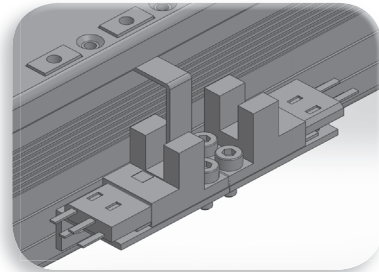
선택사양 Option



⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	Without Sensor (Standard)	E1	SUNX (PM-Y54)
		E2	OMRON (EE-SX674A)
		E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment		
R1	LM Rail-Raydent	S1	Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2	Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent		
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent		

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)	
G**	With Reduction Gear	
**	Reduction Gear Ratio 03~10	

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot Ball Screw Type
PHRC

사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	50 ~ 250
Positioning Repeatability		±0.02 (Rolled C7)
Drive System	mm	Ball Screw Ø8
Guide		1 Way 9 – 1UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Cover		Steel Band
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

허용 이격 거리 Allowable Overhang Distance

Installation Types Load capacity		Setting Angle	Allowable Overhang Distance (mm)			
			3kg	5kg	7kg	10kg
Horizontal Use		0°	85	45	35	20
		45°	105	60	40	25
		90°	320	180	125	80
Wall Mount Use		0°	260	130	70	20
		45°	60	38	18	–
		90°	100	60	45	–
Vertical Use		0°	65	40	28	20
		45°	45	30	20	14
		90°	65	40	28	20
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 50W		AC Servo Motor 100W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
0802-C7	L	100	9kg	4kg	13kg	6kg
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)									
DIA	Lead	50	100	150	200	250	300	350	400	450	500
Ø8	2	100									

이송거리별 무게 Weight by Stroke

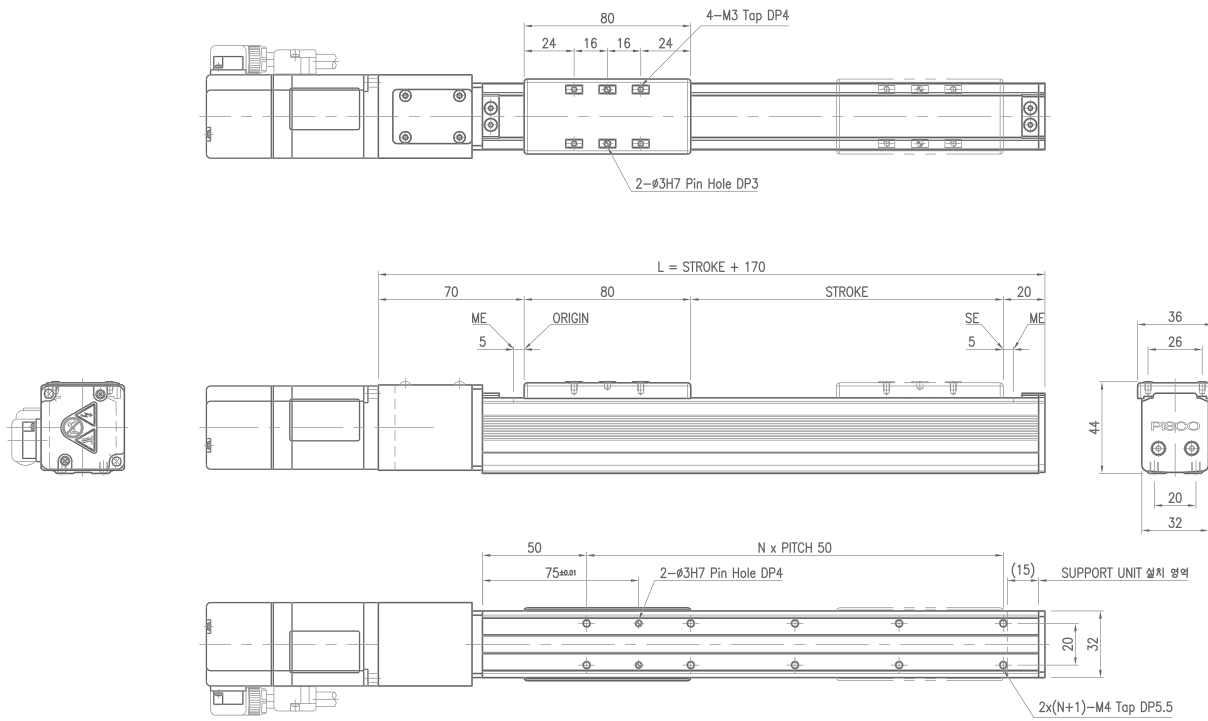
PHRC030 Robot			Stroke (mm) & Weight (kg)									
Motor	DIA	Type	50	100	150	200	250	300	350	400	450	500
100W	Ø8	S	4.4	4.9	5.4	5.9	6.4					
		P	4.3	4.8	5.3	5.8	6.3					

Clean Robot
Ball Screw Type

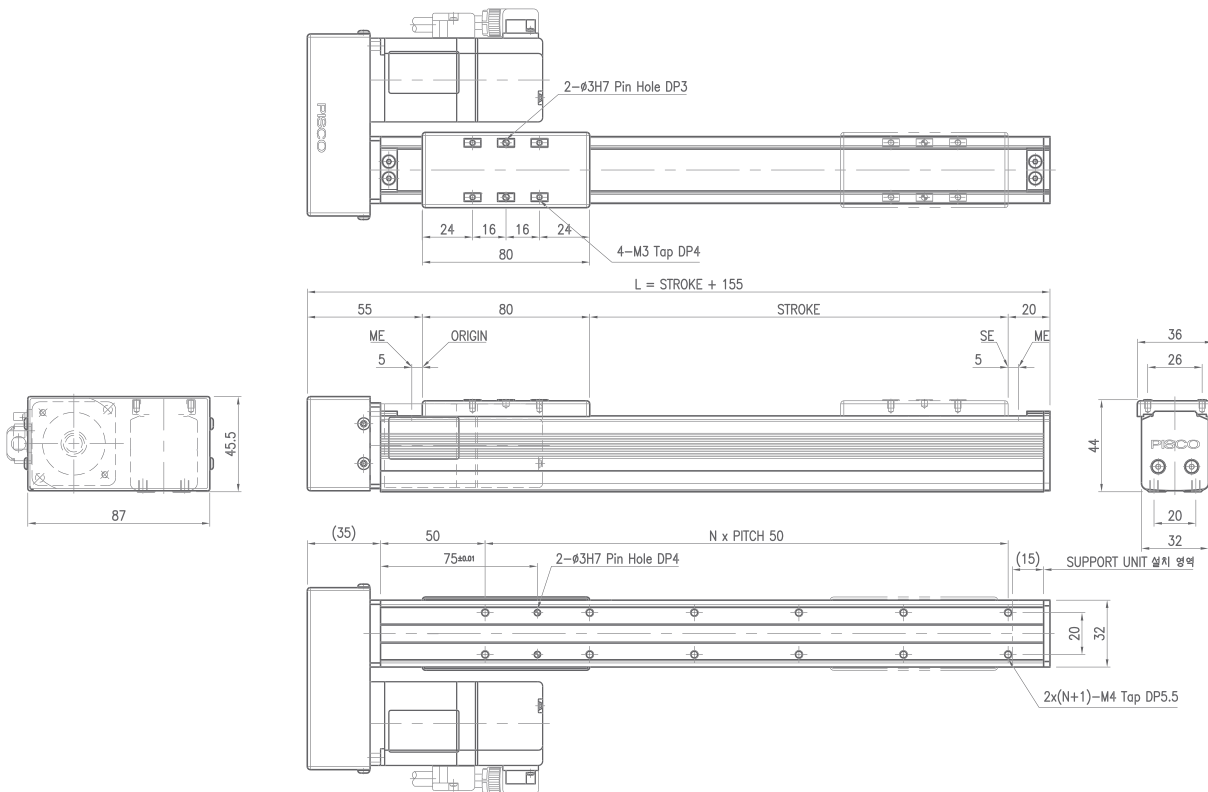
PHRC

치수도 Dimension (mm)

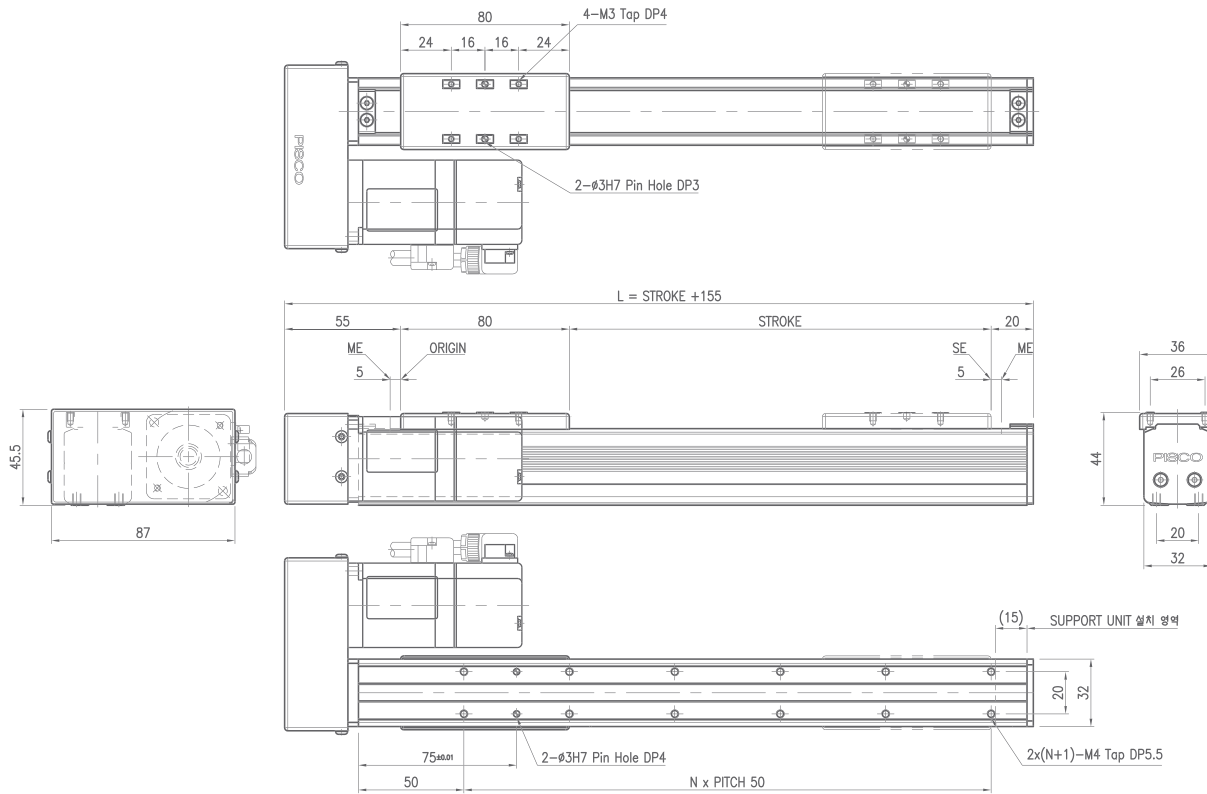
PHRC030-S-10



PHRC030-L-10

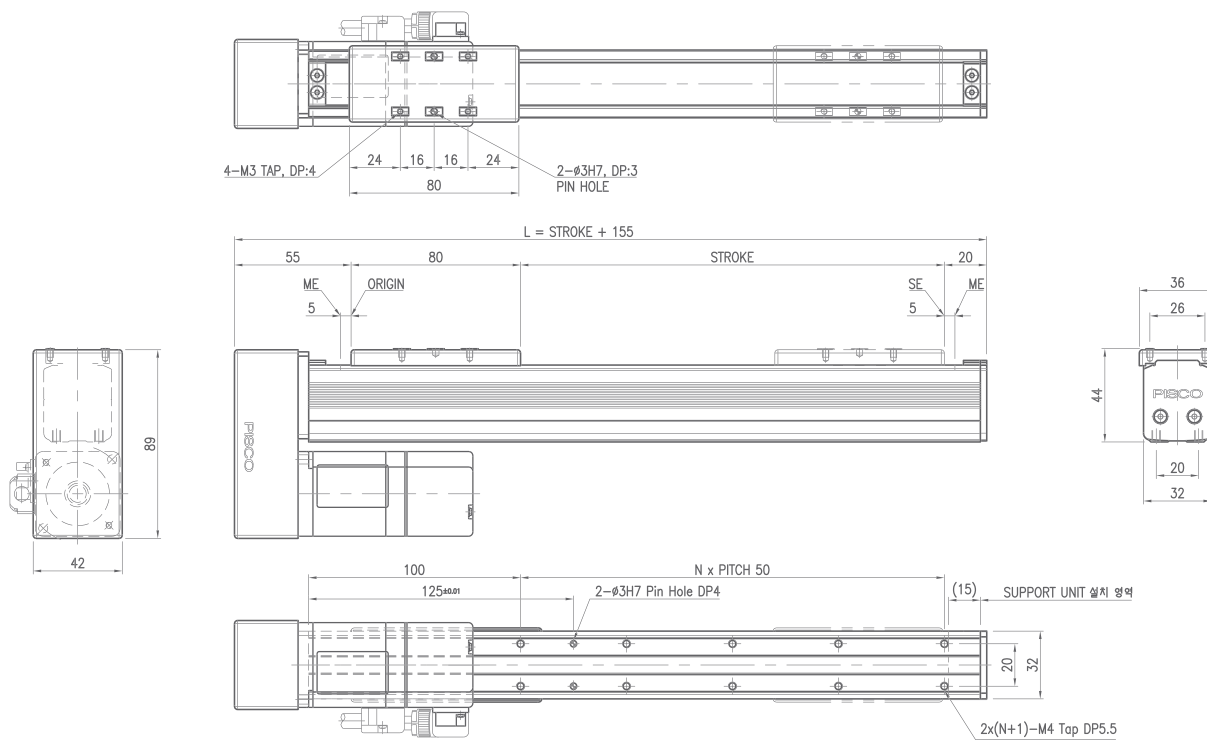


PHRC030-R-10



PHRC
Clean Robot
Ball Screw Type

PHRC030-U-10



PHRC Series

주문형식 Order Information



① 형식 Type

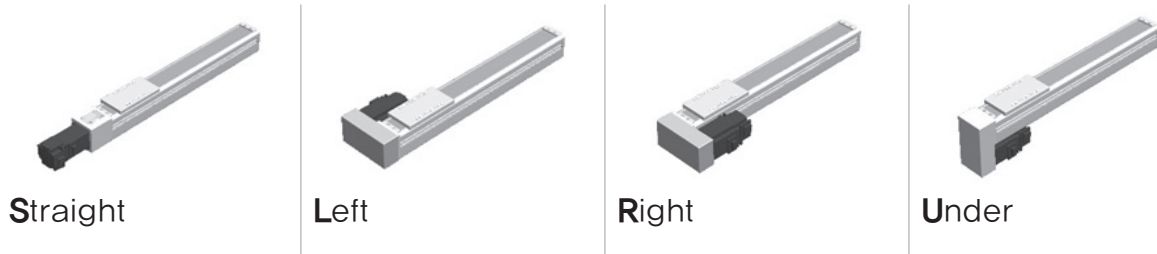
C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

40 40mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	200	400	600	800	1000
L : 1205-C7		Available	Available	Available	Available	Available
N : 1210-C7		Available	Available	Available	Available	Available

⑤ 모터용량 Motor capacity

5 50W **10** 100W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s

※ 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

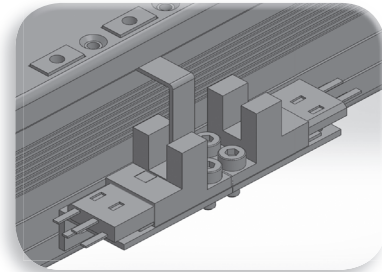
선택사양 Option



⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	Without Sensor (Standard)	E1	SUNX (PM-Y54)
		E2	OMRON (EE-SX674A)
		E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment		
R1	LM Rail-Raydent	S1	Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2	Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent		
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent		

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)	
G**	With Reduction Gear	
**	Reduction Gear Ratio 03~10	

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot Ball Screw Type
PHRC

사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 500
Positioning Repeatability		±0.02 (Bollod C7)
Drive System	mm	Ball Screw Ø12
Guide		1 Way 12 – 1UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Cover		Steel Band
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

허용 이격 거리 Allowable Overhang Distance

Installation Types Load capacity		Setting Angle	Allowable Overhang Distance (mm)			
			3kg	5kg	7kg	10kg
Horizontal Use		0°	85	45	35	20
		45°	105	60	40	25
		90°	320	180	125	80
Wall Mount Use		0°	260	130	70	20
		45°	60	38	18	–
		90°	100	60	45	–
Vertical Use		0°	65	40	28	20
		45°	45	30	20	14
		90°	65	40	28	20
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 50W		AC Servo Motor 100W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
1205-C7	L	250	9kg	4kg	13kg	6kg
1210-C7	N	500	5kg	2kg	9kg	4kg
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)										
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	
Ø12	5	250										
	10	500										

이송거리별 무게 Weight by Stroke

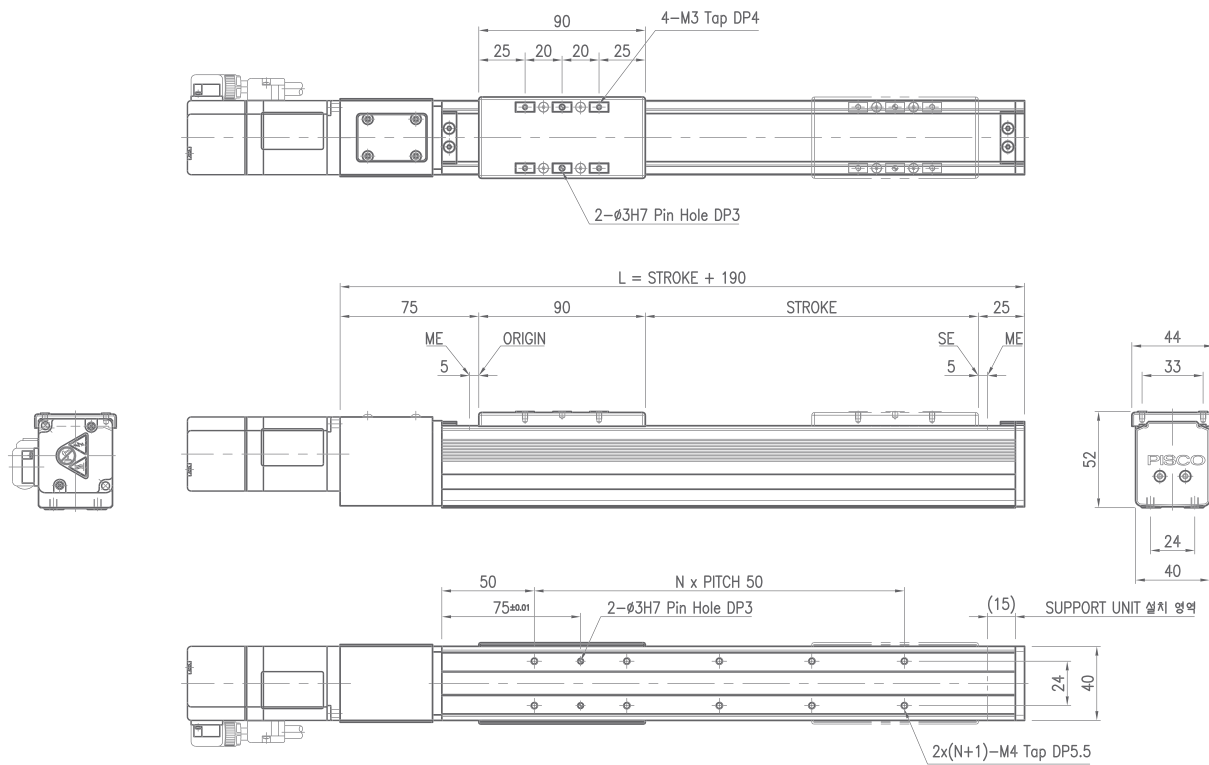
PHRC040 Robot			Stroke (mm) & Weight (kg)									
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000
100W	Ø12	S	4.4	4.9	5.4	5.9	6.4					
		P	4.3	4.8	5.3	5.8	6.3					

Clean Robot
Ball Screw Type

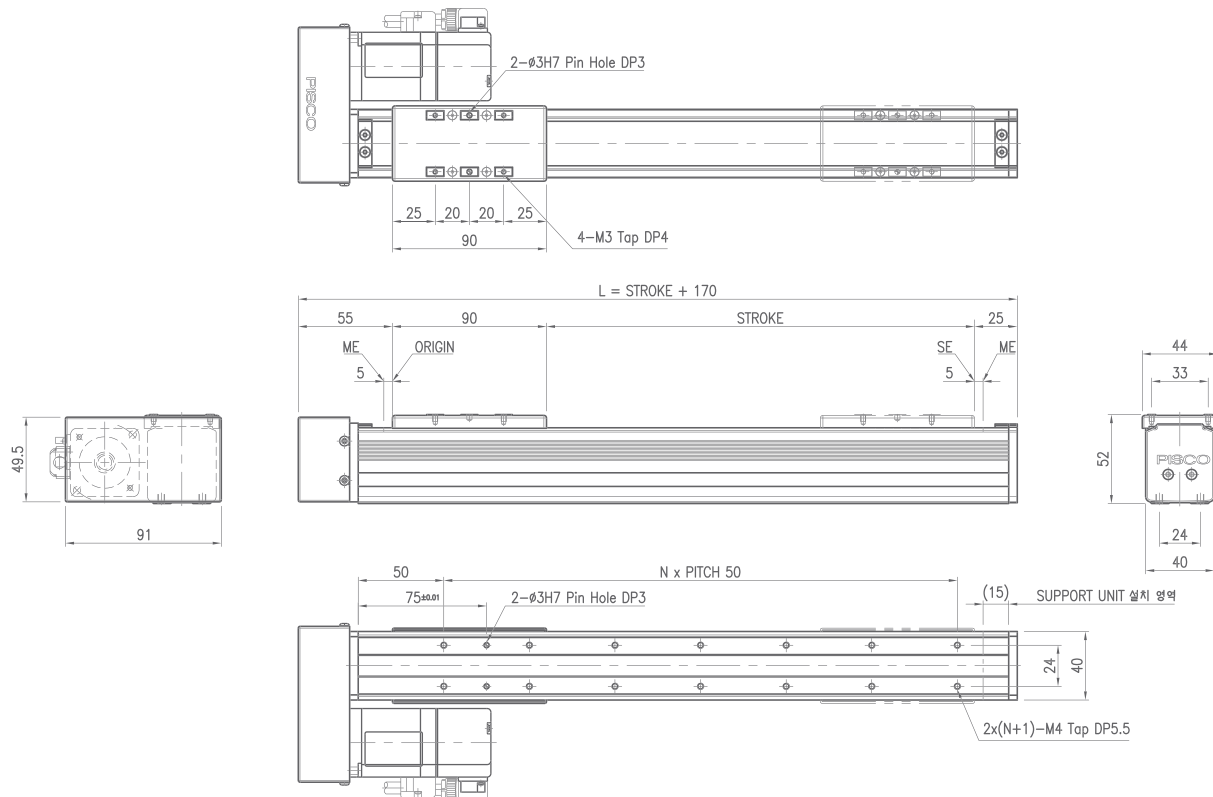
PHRC

치수도 Dimension (mm)

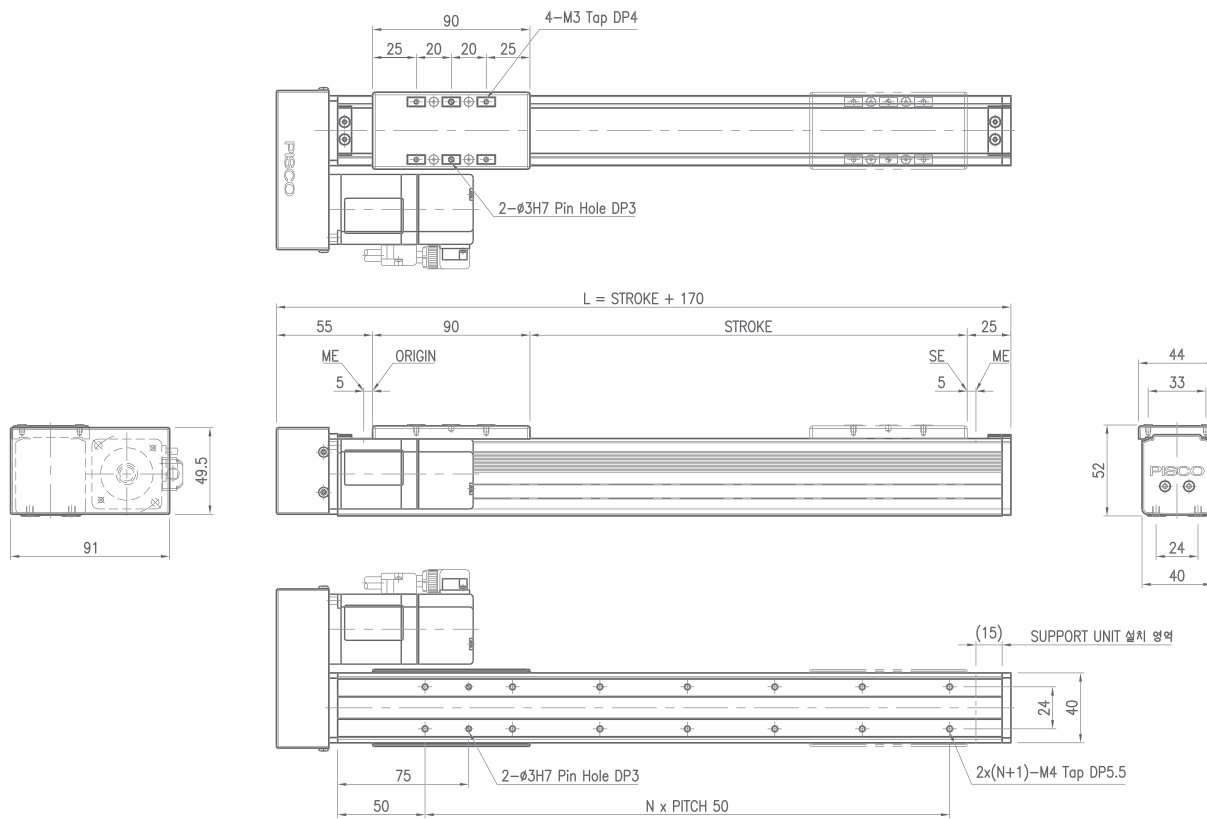
PHRC040-S-10



PHRC040-L-10

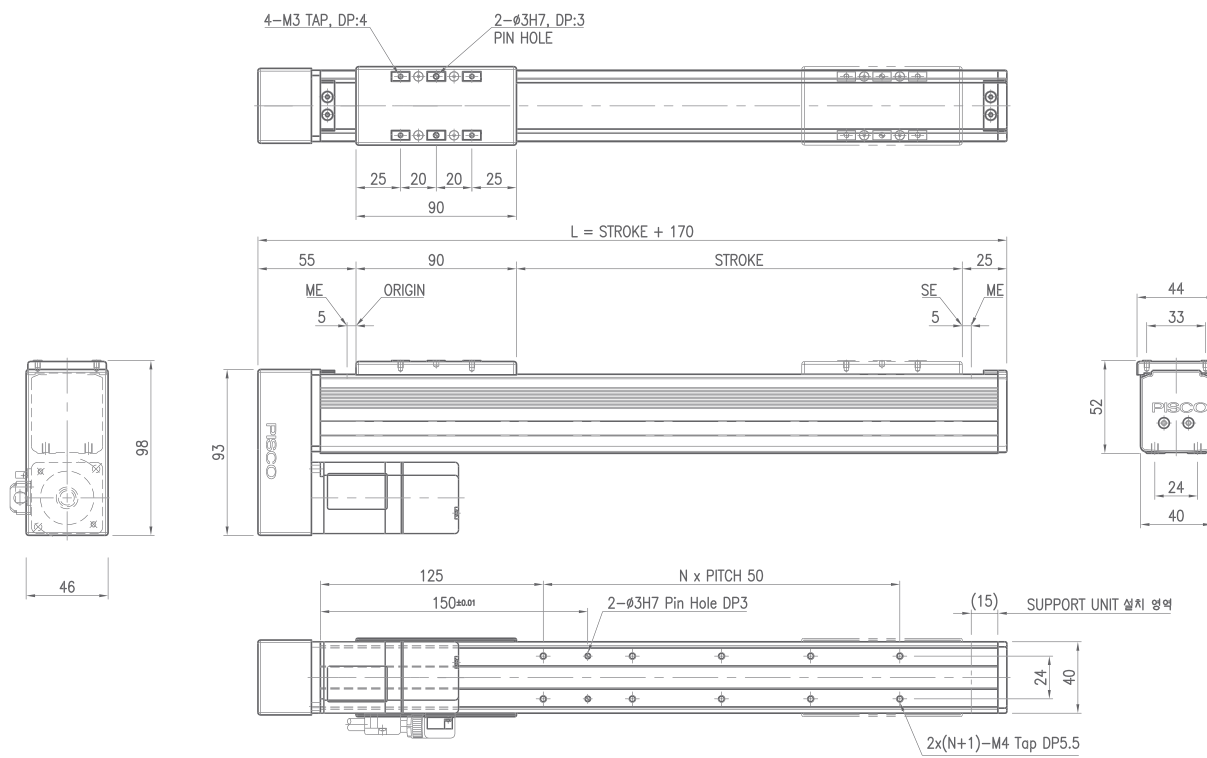


PHRC040-R-10



PHRC
Clean Robot
Ball Screw Type

PHRC040-U-10



PHRC Series

주문형식 Order Information



① 형식 Type

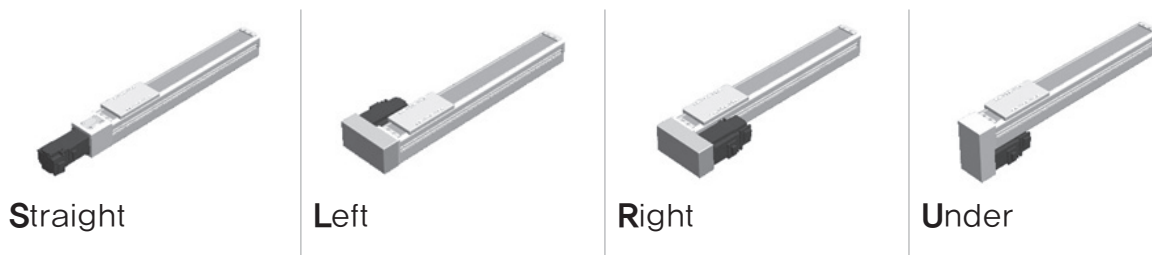
C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

50 50mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	200	400	600	800	1000
L : 1205-C7		■	■			
N : 1210-C7		■	■			

⑤ 모터용량 Motor capacity

5 50W **10** 100W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s

※ 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

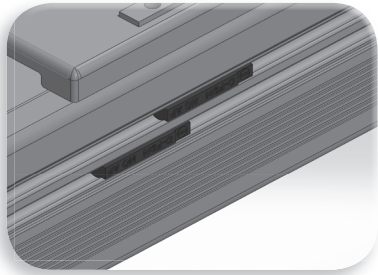
선택사양 Option



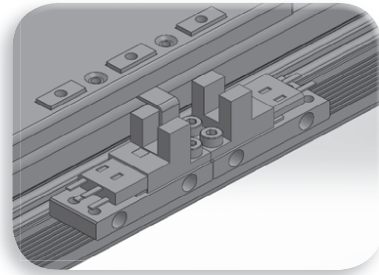
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment	
R1	LM Rail-Raydent	S1 Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2 Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent	
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent	

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot
Ball Screw Type

PHRC

사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 500
Positioning Repeatability		±0.02 (Rolled C7)
Drive System	mm	Ball Screw Ø12
Guide		1 Way 24 – 1UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Cover		Steel Band
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

허용 이격 거리 Allowable Overhang Distance

Installation Types Load capacity		Setting Angle	Allowable Overhang Distance (mm)			
			3kg	5kg	7kg	10kg
Horizontal Use		0°	85	45	35	20
		45°	105	60	40	25
		90°	320	180	125	80
Wall Mount Use		0°	260	130	70	20
		45°	60	38	18	–
		90°	100	60	45	–
Vertical Use		0°	65	40	28	20
		45°	45	30	20	14
		90°	65	40	28	20
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 50W		AC Servo Motor 100W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
1205-C7	L	250	9kg	4kg	13kg	6kg
1210-C7	N	500	5kg	2kg	9kg	4kg
Estimated Condition	Stroke : 200mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)										
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	
Ø12	5	250										
	10	500										

이송거리별 무게 Weight by Stroke

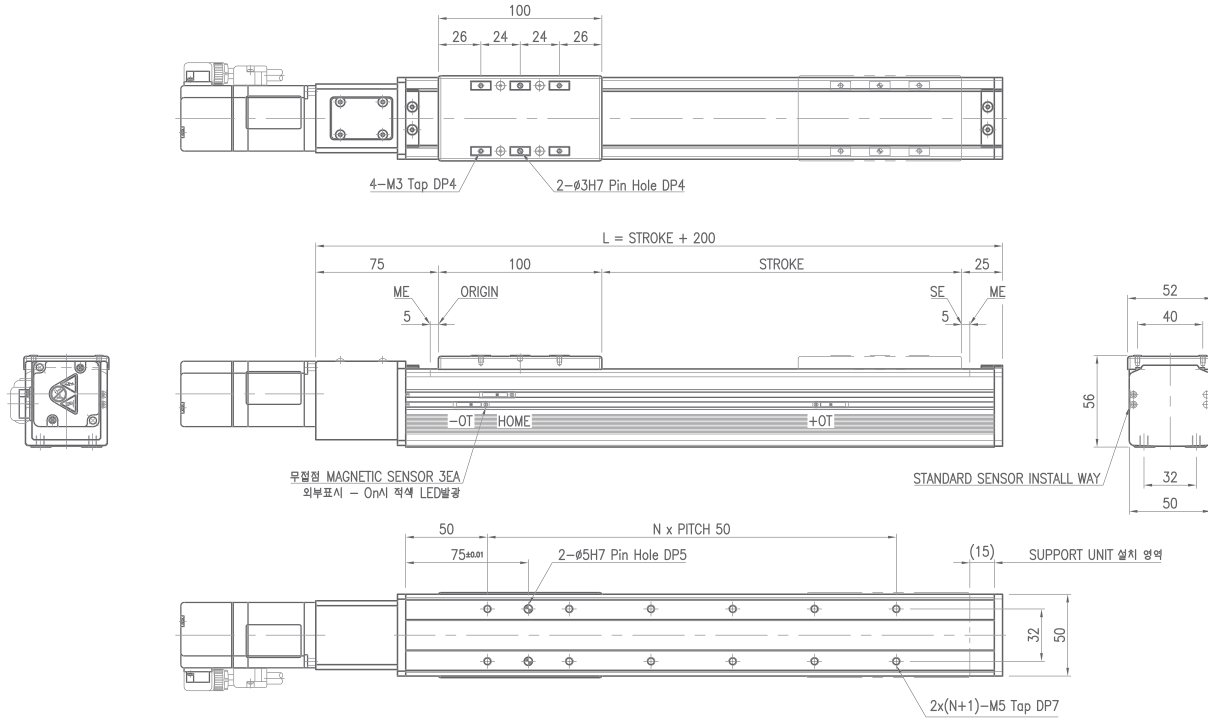
PHRC050 Robot			Stroke (mm) & Weight (kg)									
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000
100W	Ø12	S	4.4	4.9	5.4	5.9	6.4					
		P	4.3	4.8	5.3	5.8	6.3					

Clean Robot
Ball Screw Type

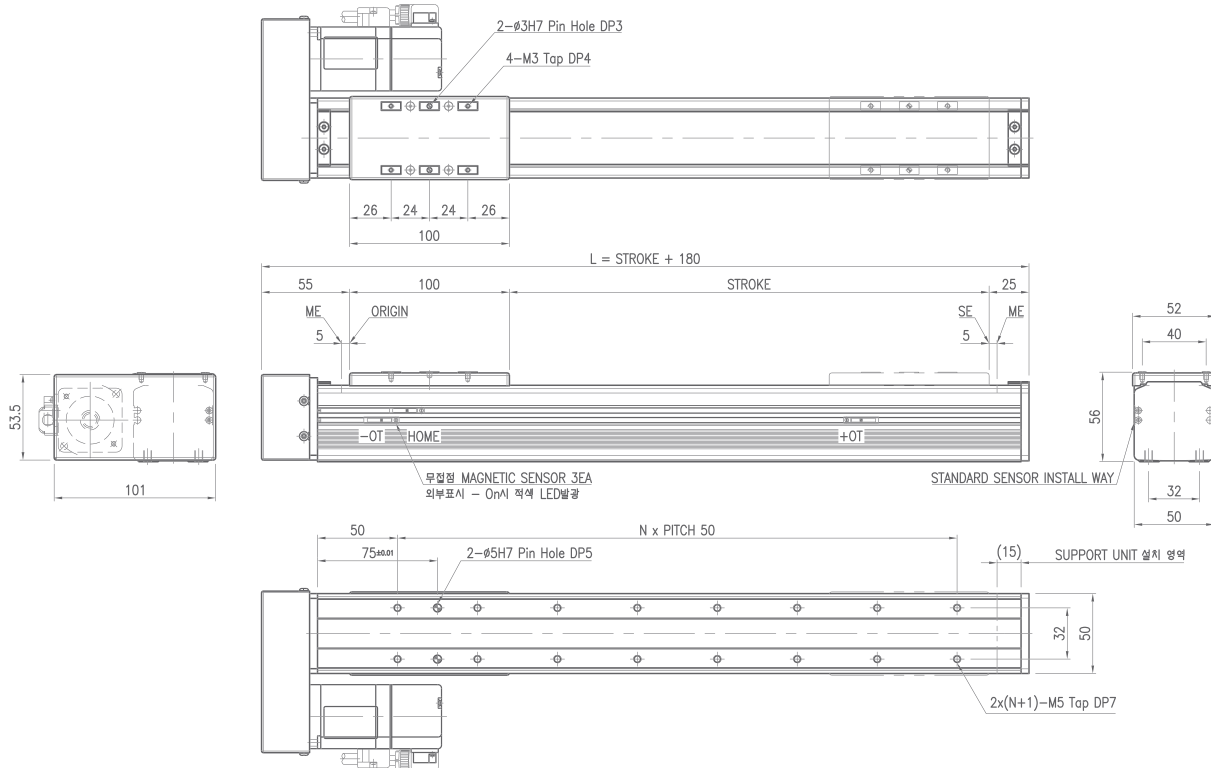
PHRC

치수도 Dimension (mm)

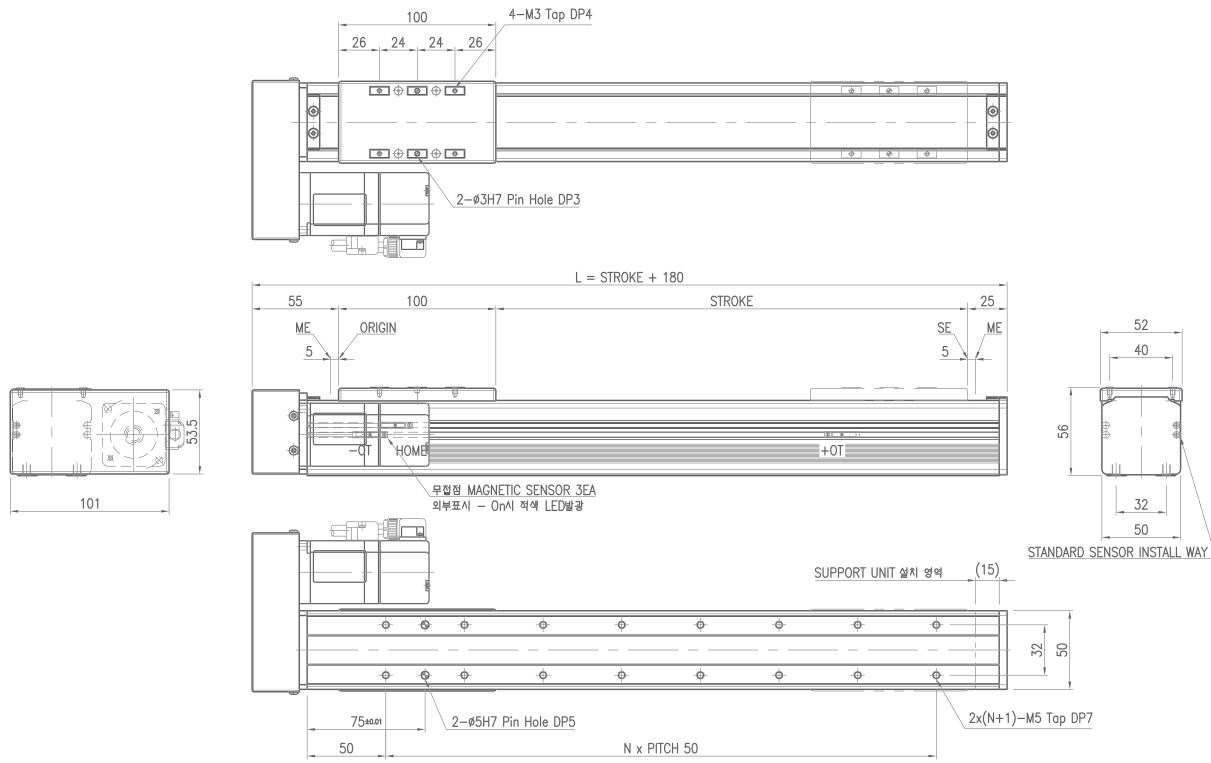
PHRC050-S-10



PHRC050-L-10

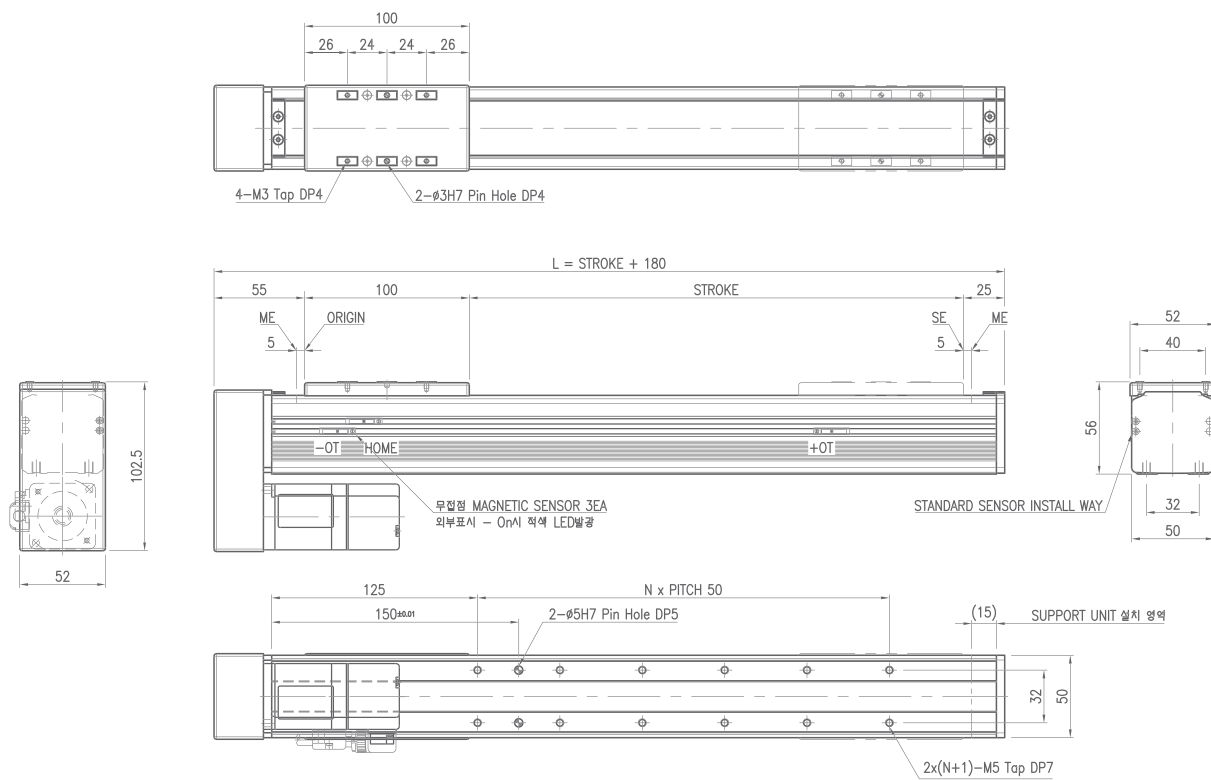


PHRC050-R-10



Clean Robot
Ball Screw Type
PHRC

PHRC050-U-10



PHRC Series

주문형식 Order Information



① 형식 Type

C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

70 70mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	1000	1500	2000	2500
L : 1505-C7		████████████████████			
N : 1510-C7		████████████████████			
H : 1520-C7		██			

⑤ 모터용량 Motor capacity

10 100W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s **H** 1000mm/s
P(*2) 1500mm/s

*1 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

*2 상기 사양은 특수사양으로 피스코코리아 모션사업부에 문의하여 주십시오.

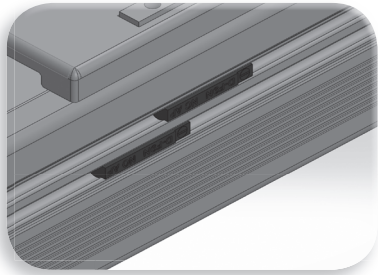
선택사양 Option



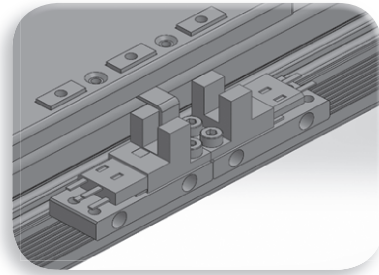
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment		
R1	LM Rail-Raydent	S1	Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2	Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent		
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent		

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot
Ball Screw Type

PHRC


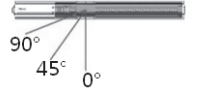
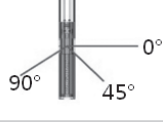
사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 1800
Positioning Repeatability		±0.02 (Ground C7), ±0.01 (Ground C5)
Drive System	mm	Ball Screw Ø15
Guide		1 Way 24 – 2UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Main & Side Cover		Steel Band & Aluminum Profile, Soft White Anodizing(※)
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

※ Side Cover에 Transparent PC Extrude Profile의 사양은 특주로 대응됩니다.

허용 이격 거리 Allowable Overhang Distance

Installation Types	Load capacity	Setting Angle	Allowable Overhang Distance (mm)			
			6kg	9kg	12kg	15kg
Horizontal Use		0°	115	70	50	38
		45°	105	67	46	35
		90°	620	400	280	200
Wall Mount Use		0°	250	–	–	–
		45°	35	–	–	–
		90°	35	–	–	–
Vertical Use		0°	110	65	40	30
		45°	50	25	15	8
		90°	100	55	30	15
Estimated Condition	Stroke : 1000mm Speed : 1000mm/sec Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 100W	
	Mark	mm/s	Horizontal	Vertical
1505-C7	L	250	15kg	15kg
1510-C7	N	500	15kg	10kg
1520-C7	H	1000	8kg	4kg
Estimated Condition	Stroke : 500mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm			

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)																														
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500						
Ø15	5						250	211	169	138	115	98	84	73																		
	10						500	421	337	276	231	195	168	145																		
	20						1000	842	675	553	461	390	335	290	254	224	200	179	161													

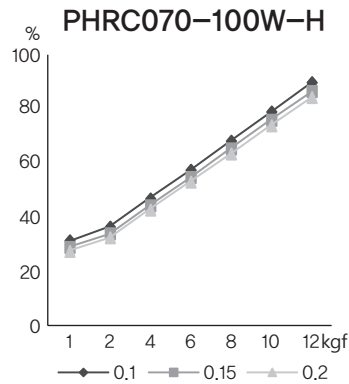
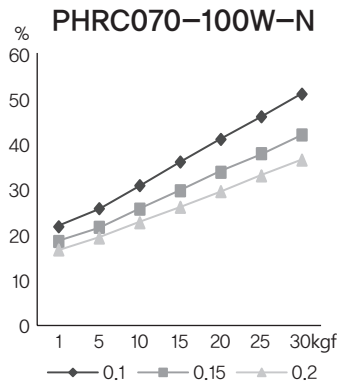
이송거리별 무게 Weight by Stroke

PHRC070 Robot			Stroke (mm) & Weight (kg)																											
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500			
100W	Ø15	S	4.5	5.0	5.5	6.0	6.5	7.0	7.5	7.9	8.4	8.9	9.4	9.9	10.4	10.9	11.4	11.9	12.4	12.8										
		P	4.5	5.0	5.5	5.9	6.4	6.9	7.4	7.9	8.4	8.9	9.4	9.9	10.4	10.8	11.3	11.8	12.3	12.8										

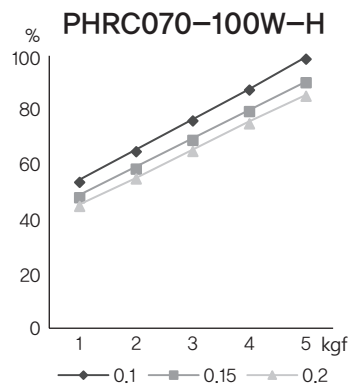
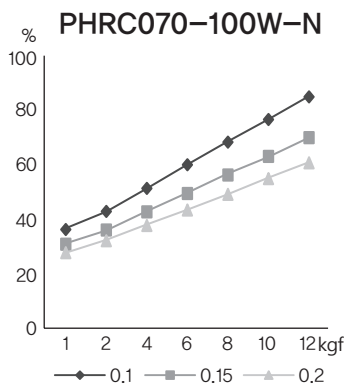
Clean Robot Ball Screw Type
PHRC

가속시간별 부하율표 Accelerating Time & Pay Load

수평이송 Horizontal

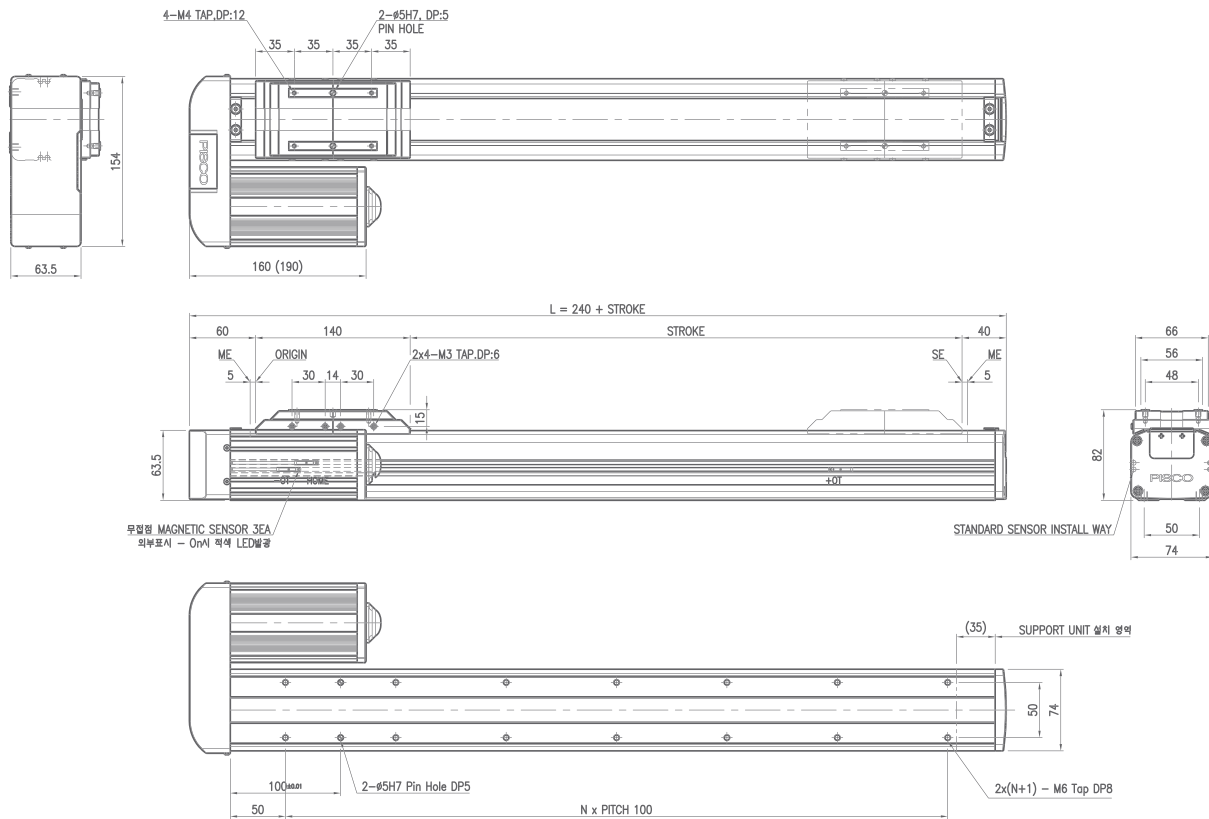


수직이송 Vertical



PHRC070-R-10

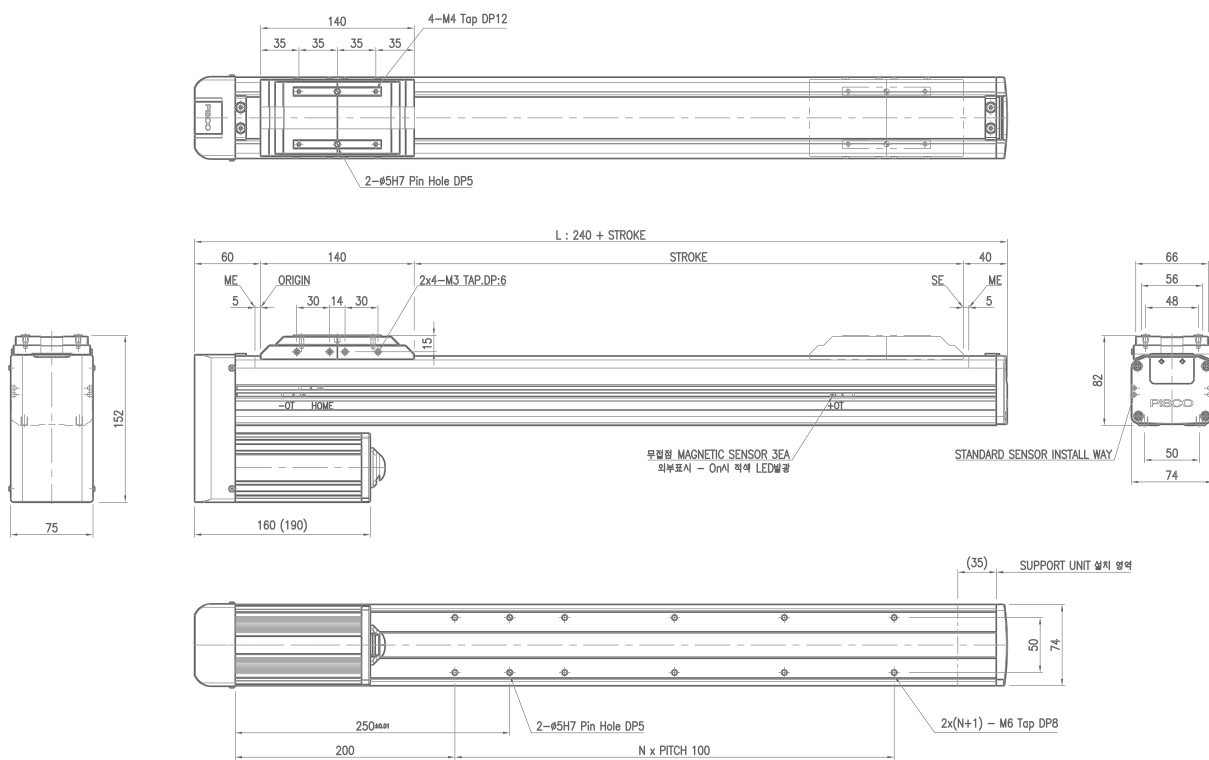
※ () Brake Motor Dimension



PHRC
Clean Robot
Ball Screw Type

PHRC070-U-10

※ () Brake Motor Dimension



PHRC Series

주문형식 Order Information



① 형식 Type

C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

90 90mm

③ 형상 Shape

Normal Type



Straight



Left



Right



Under

④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	1000	1500	2000	2500
L : 1505-C7		1000	1500		
N : 1510-C7		1000	1500		
H : 1520-C7		1000	1500	2000	2500
P : 1530-C7		1000	1500	2000	2500

⑤ 모터용량 Motor capacity

10 100W **20** 200W **40** 400W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s **H** 1000mm/s
P 1500mm/s **S(*2)** 2000mm/s **U(*2)** 3000mm/s

*1 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

*2 상기 사양은 특수사양으로 피스코코리아 모션사업부에 문의하여 주십시오.

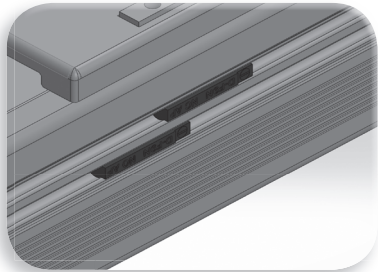
선택사양 Option



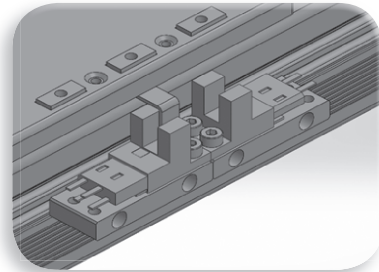
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment	
R1	LM Rail-Raydent	S1 Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2 Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent	
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent	

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cavveyor
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Clean Robot
Ball Screw Type

PHRC


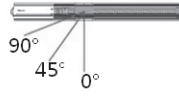
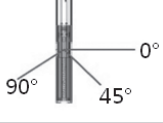
사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 1800
Positioning Repeatability		±0.02 (Ground C7), ±0.01 (Ground C5)
Drive System	mm	Ball Screw Ø15
Guide		1 Way 42 – 2UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Main & Side Cover		Steel Band & Aluminum Profile, Soft White Anodizing(※)
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

※ Side Cover에 Transparent PC Extrude Profile의 사양은 특주로 대응됩니다.

허용 이격 거리 Allowable Overhang Distance

Installation Types	Load capacity	Setting Angle	Allowable Overhang Distance (mm)			
			5kg	10kg	20kg	30kg
Horizontal Use		0°	390	190	85	50
		45°	350	162	70	42
		90°	1000	760	330	190
Wall Mount Use		0°	1100	440	70	–
		45°	233	78	7	–
		90°	270	90	10	–
Vertical Use		0°	260	120	40	–
		45°	142	56	20	6
		90°	300	125	40	13
Estimated Condition	Stroke : 1000mm Speed : 1000mm/sec Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 100W		AC Servo Motor 200W		AC Servo Motor 400W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical
1505-C7	L	250	30kg	22kg	30kg	30kg	30kg	30kg
1510-C7	N	500	30kg	10kg	30kg	22kg	30kg	30kg
1520-C7	H	1000	8kg	4kg	30kg	10kg	30kg	22kg
1530-C7	P	1500	2kg	2kg	12kg	6kg	24kg	14kg
Estimated Condition	Stroke : 500mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm							

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)																										
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500		
Ø15	5	250						211	169	138	116	98	84	73														
	10	500						422	338	277	231	196	168	146														
	20	1000						844	676	554	462	391	335	291	255	225	200	179	161									
	30	1500						1266	1014	831	693	587	503	437	382	337	300	269	242									

이송거리별 무게 Weight by Stroke

PHRC090 Robot			Stroke (mm) & Weight (kg)																										
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500		
100W	Ø15	S	6.3	7.0	7.7	9.1	9.8	10.7	11.6	12.6	13.5	14.4	15.3	16.2	17.2	18.1	19.0	19.9	20.8	21.8									
		P	6.2	6.9	7.6	9.0	9.7	10.6	11.5	12.5	13.4	14.3	15.2	16.1	17.1	18.0	18.9	19.8	20.7	21.7									
200W	Ø15	S	6.7	7.4	8.1	8.8	9.5	10.2	10.9	11.6	12.3	13.0	13.7	14.4	15.1	15.8	16.6	17.3	18.0	18.7									
		P	6.5	7.2	7.9	8.6	9.3	10.0	10.7	11.4	12.1	12.8	13.5	14.2	15.0	15.7	16.4	17.1	17.8	18.5									
400W	Ø15	S	7.3	8.0	8.7	9.4	10.1	10.8	11.5	12.2	12.9	13.7	14.4	15.1	15.8	16.5	17.2	17.9	18.6	19.3									
		P	7.1	7.8	8.5	9.2	9.9	10.6	11.4	12.1	12.8	13.5	14.2	14.9	15.6	16.3	17.0	17.7	18.4	19.1									

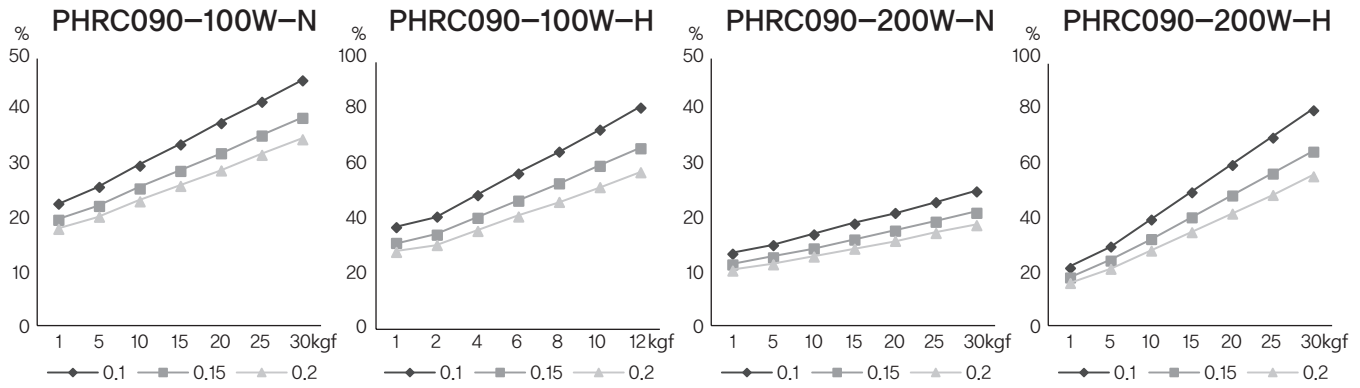
Clean Robot
Ball Screw Type

PHRC

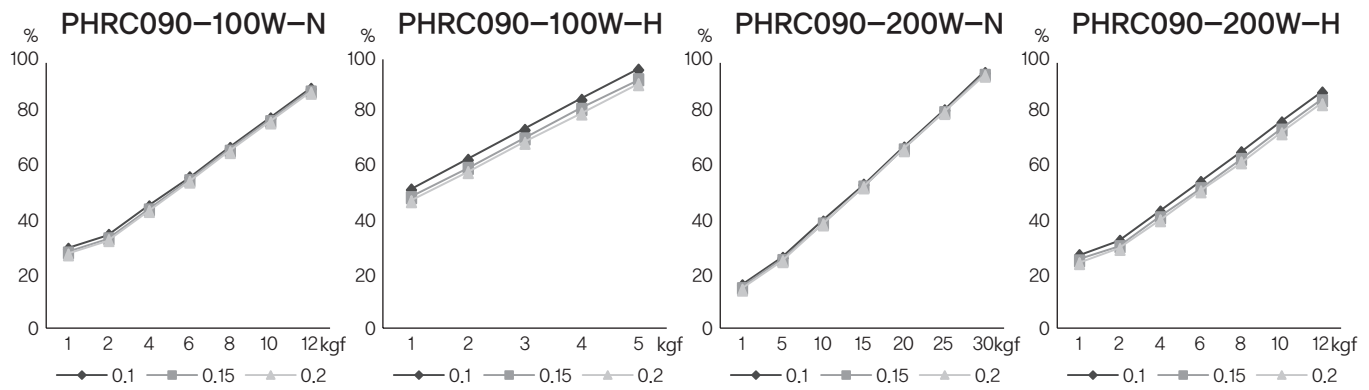
사양 Specifications

가속시간별 부하율표 Accelerating Time & Pay Load

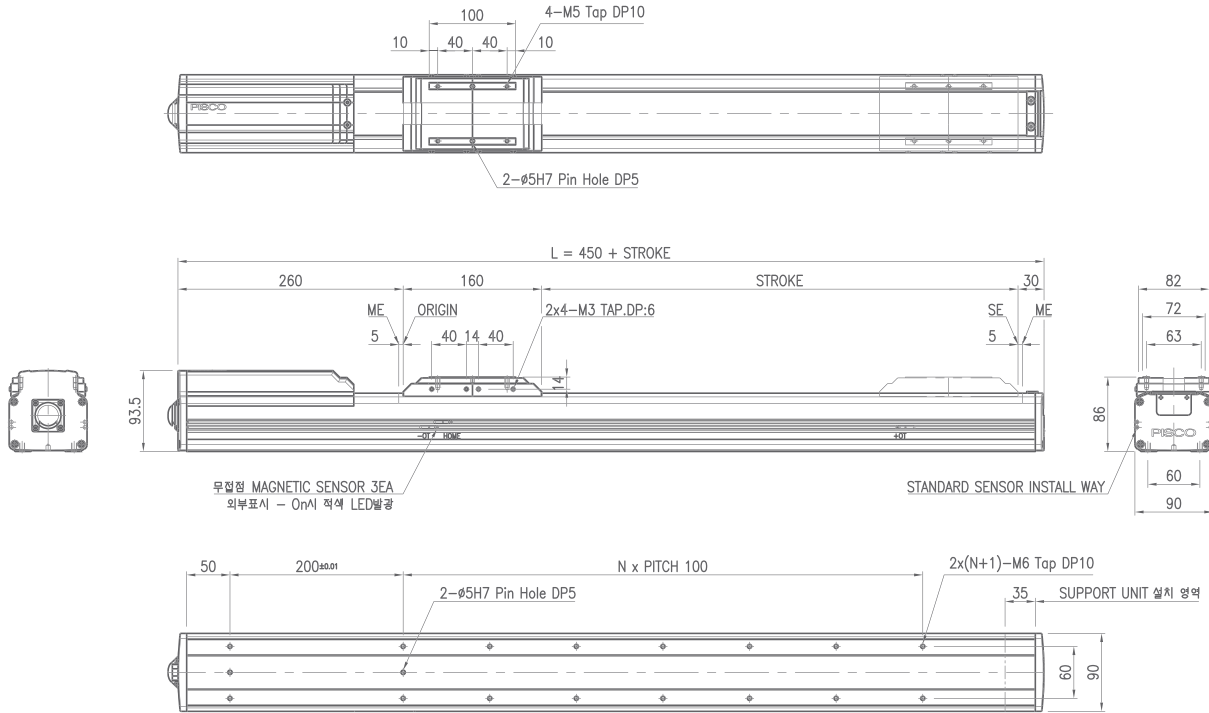
수평이송 Horizontal



수직이송 Vertical



PHRC090-S-20(40)

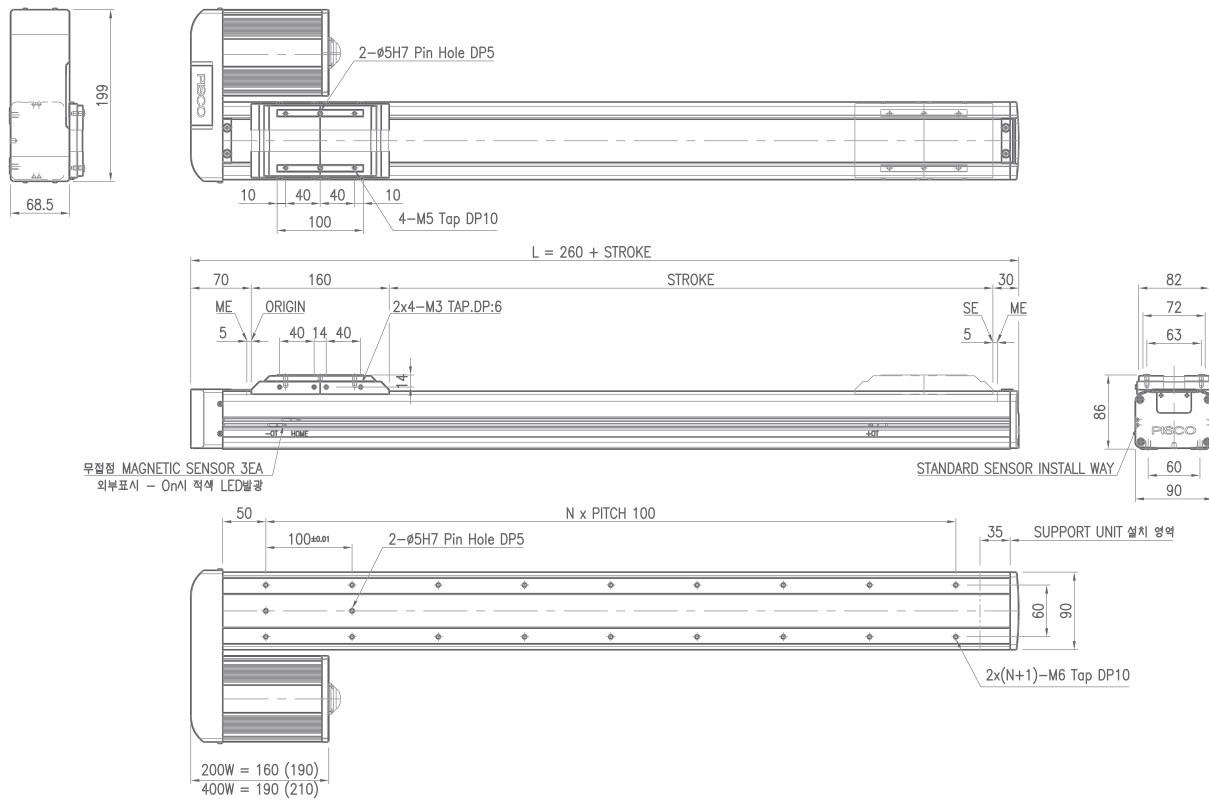


Clean Robot Ball Screw Type

PHRC

PHRC090-L-20(40)

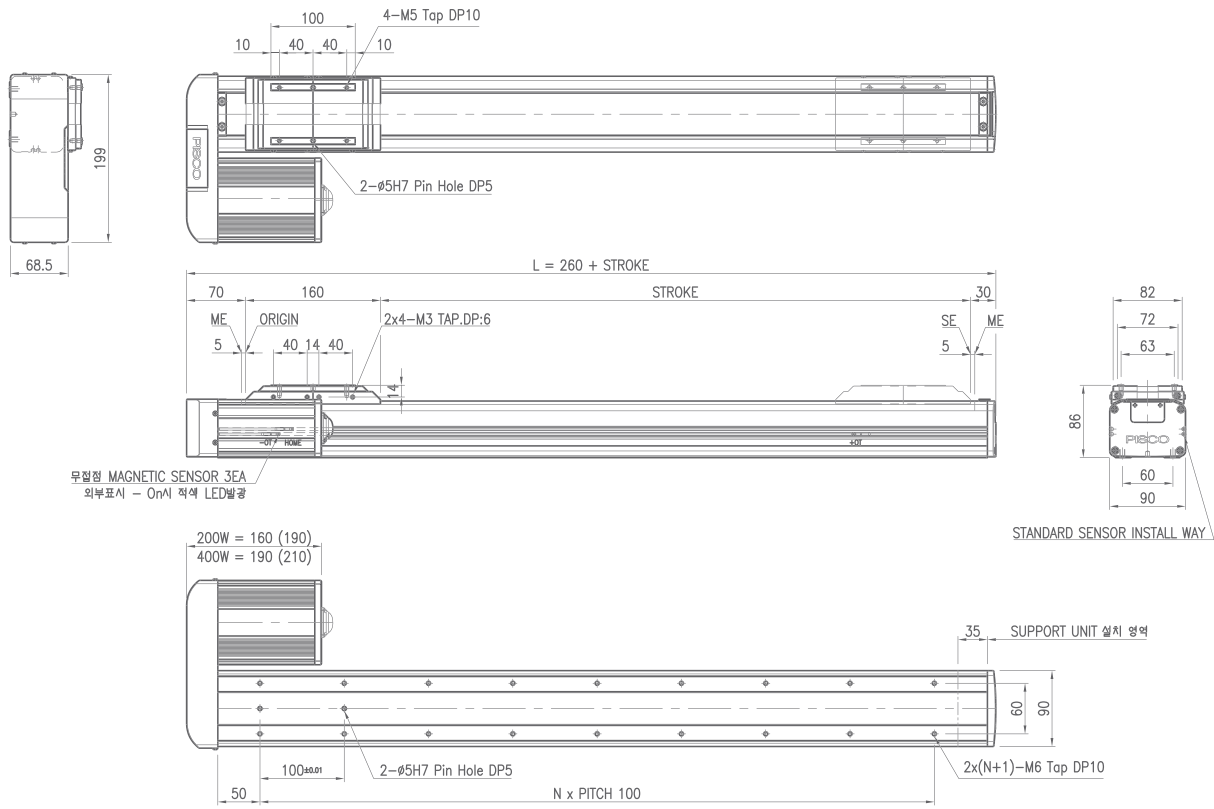
※ () Brake Motor Dimension



치수도 Dimension (mm)

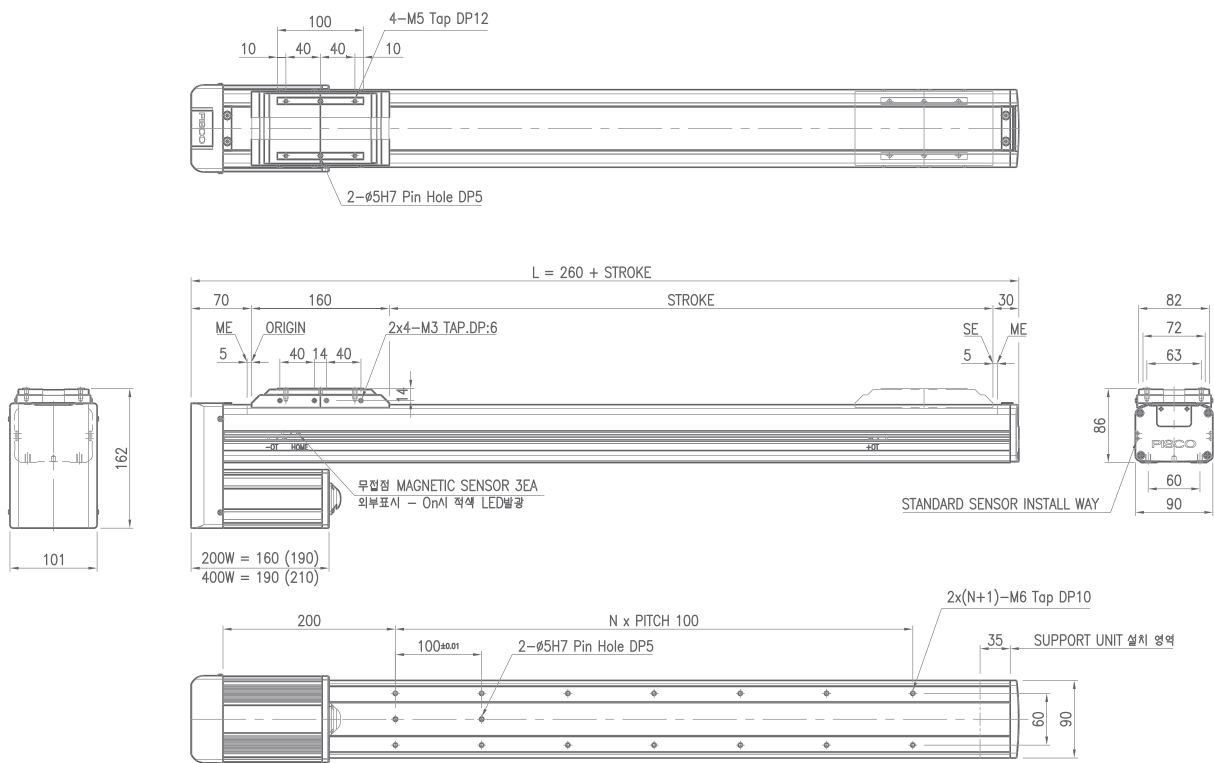
PHRC090-R-20(40)

※ () Brake Motor Dimension



PHRC090-U-20(40)

※ () Brake Motor Dimension



Clean Robot
Ball Screw Type

PHRC

PHRC Series

주문형식 Order Information



① 형식 Type

C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

120 120mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	1000	1500	2000	2500
L : 1505-C7	1000				
N : 1510-C7	1000				
H : 1520-C7	1500				
P : 1530-C7	1500				
L : 2005-C7(*)	1500				
N : 2010-C7(*)	1500				
H : 2020-C7(*)	2000				
P : 2030-C7(*)	2000				
S : 2040-C7(*)	2000				

* 볼나사 규격 20□□의 경우 모두 특주로 대응됩니다.

⑤ 모터용량 Motor capacity

20 200W **40** 400W Option **10** 100W Option **75** 750W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s **H** 1000mm/s
P 1500mm/s **S(*2)** 2000mm/s **U(*2)** 3000mm/s

*1 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

*2 상기 사양은 특주사양으로 피스코코리아 모션사업부에 문의하여 주십시오.

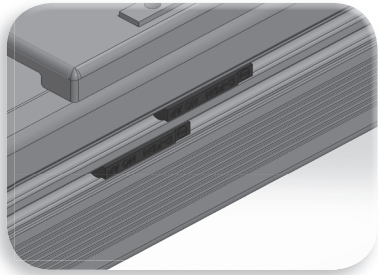
선택사양 Option



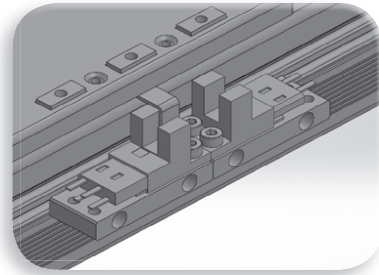
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment	
R1	LM Rail-Raydent	S1 Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2 Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent	
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent	

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot
Ball Screw Type

PHRC

사양 Specifications

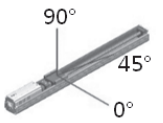
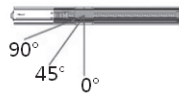
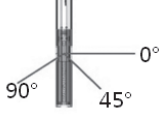
공통사양 Common Specifications

Stroke Range	mm	100 ~ 2300
Positioning Repeatability		±0.02 (Ground C7), ±0.01 (Ground C5)
Drive System	mm	Ball Screw Ø15, Ø20(※1)
Guide		2 Way 15W – 2UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Main & Side Cover		Steel Band & Aluminum Profile, Soft White Anodizing(※2)
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

※1 볼나사 규격 20□□의 경우 모두 특주로 대응됩니다.

※2 Side Cover에 Transparent PC Extrude Profile의 사양은 특주로 대응됩니다.

허용 이격 거리 Allowable Overhang Distance

Installation Types Load capacity		Setting Angle	Allowable Overhang Distance (mm)			
			20kg	30kg	40kg	50kg
Horizontal Use		0°	380	260	200	165
		45°	318	215	166	134
		90°	1000	930	700	565
Wall Mount Use		0°	760	460	300	200
		45°	233	130	81	50
		90°	290	160	100	60
Vertical Use		0°	170	100	65	45
		45°	106	63	42	32
		90°	260	155	105	70
Estimated Condition	Stroke : 1000mm Speed : 1000mm/sec Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 200W		AC Servo Motor 400W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
1505-C7	L	250	50kg	50kg	50kg	50kg
1510-C7	N	500	50kg	22kg	50kg	38kg
1520-C7	H	1000	28kg	9kg	45kg	21kg
1530-C7	P	1500	11kg	5kg	23kg	13kg
2005-C7(※)	L	250	50kg	46kg	50kg	50kg
2010-C7(※)	N	500	50kg	21kg	50kg	46kg
2020-C7(※)	H	1000	23kg	9kg	50kg	21kg
2030-C7(※)	P	1500	8kg	5kg	20kg	13kg
2040-C7(※)	S	2000	4kg	2kg	10kg	9kg
Estimated Condition	Stroke : 500mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

※ 볼나사 규격 20□□의 경우 모두 특주로 대응됩니다.

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)																								
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500
Ø15	5	250						209	167	137	115	97	83	72												
	10	500						417	335	274	229	194	167	145												
	20	1000						834	669	549	458	388	333	289	253	223	199	178	160							
	30	1500						1251	1004	823	687	582	500	434	380	335	298	267	241							
Ø20 (※)	5	250						236	193	161	137	117	102	89	79	70	63	56								
	10	500						472	387	323	274	235	204	178	158	140	125	113								
	20	1000						943	773	646	547	469	407	357	315	280	251	226	204	186	170	156	143			
	30	1500						1415	1160	969	821	704	611	535	473	420	376	339	307	279	255	234	215			
	40	2000						1887	1547	1291	1094	939	815	713	630	560	501	451	409	372	339	311	287			

※ 볼나사 규격 20□□의 경우 모두 특주로 대응됩니다.

이송거리별 무게 Weight by Stroke

PHRC120 Robot			Stroke (mm) & Weight (kg)																								
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500
200W	Ø15	S	8.2	9.0	9.9	10.7	11.6	12.4	13.3	14.1	15.0	15.8	16.7	17.6	18.4	19.3	20.1	21.0	21.8	22.7							
		P	7.8	8.6	9.5	10.3	11.2	12.0	12.9	13.7	14.6	15.4	16.3	17.2	18.0	18.9	19.7	20.6	21.4	22.3							
	Ø20 (※)	S	8.8	9.8	10.8	11.8	12.8	13.8	14.8	15.8	16.8	17.8	18.8	19.8	20.8	21.8	22.8	23.8	24.9	25.9	26.9	27.9	28.9	29.9	30.9		
		P	8.3	9.3	10.3	11.3	12.3	13.3	14.3	15.3	16.3	17.3	18.3	19.3	20.3	21.3	22.3	23.3	24.3	25.3	26.3	27.3	28.3	29.3	30.3		
400W	Ø15	S	9.0	9.9	11.6	12.5	13.7	14.9	16.1	17.3	18.5	19.7	20.9	22.1	23.3	24.5	25.7	26.9	28.1	29.3							
		P	8.5	9.4	11.1	11.9	13.2	14.4	15.6	16.8	18.0	19.2	20.4	21.6	22.8	24.0	25.2	26.4	27.6	28.8							
	Ø20 (※)	S	9.4	10.4	11.4	12.4	13.4	14.4	15.4	16.4	17.4	18.4	19.4	20.4	21.4	22.4	23.5	24.5	25.5	26.5	27.5	28.5	29.5	30.5	31.5		
		P	8.8	9.8	10.8	11.8	12.8	13.8	14.9	15.9	16.9	17.9	18.9	19.9	20.9	21.9	22.9	23.9	24.9	25.9	26.9	27.9	28.9	29.9	30.9		

※ 볼나사 규격 20□□의 경우 모두 특주로 대응됩니다.

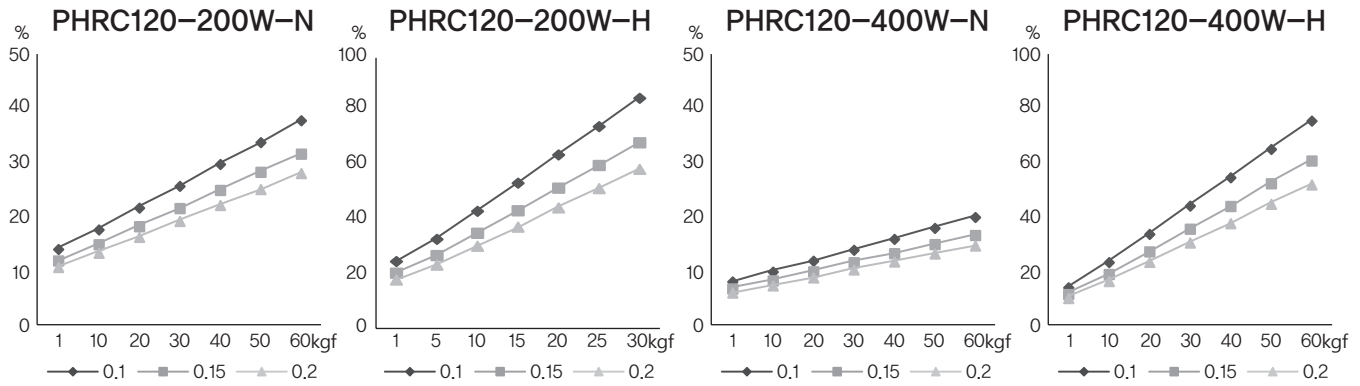
Clean Robot
Ball Screw Type

PHRC

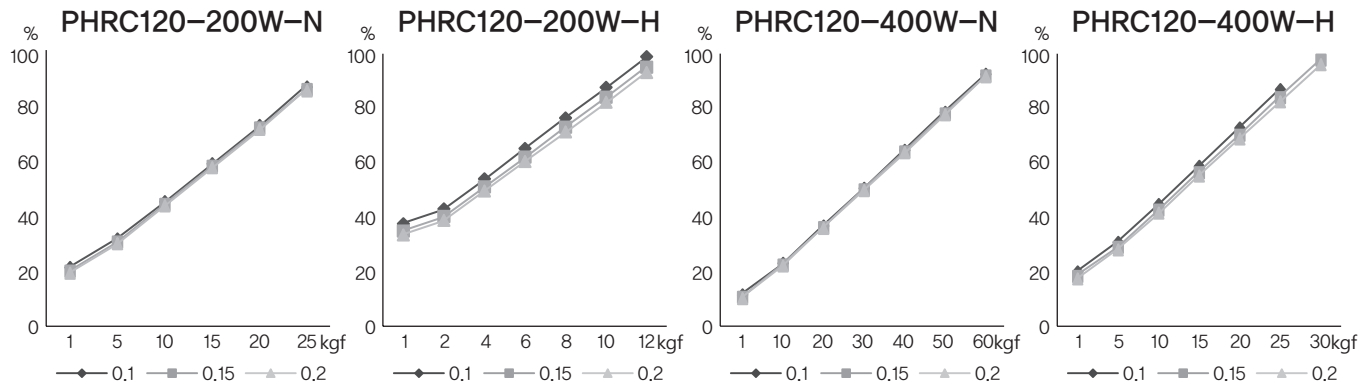
사양 Specifications

가속시간별 부하율표 Accelerating Time & Pay Load

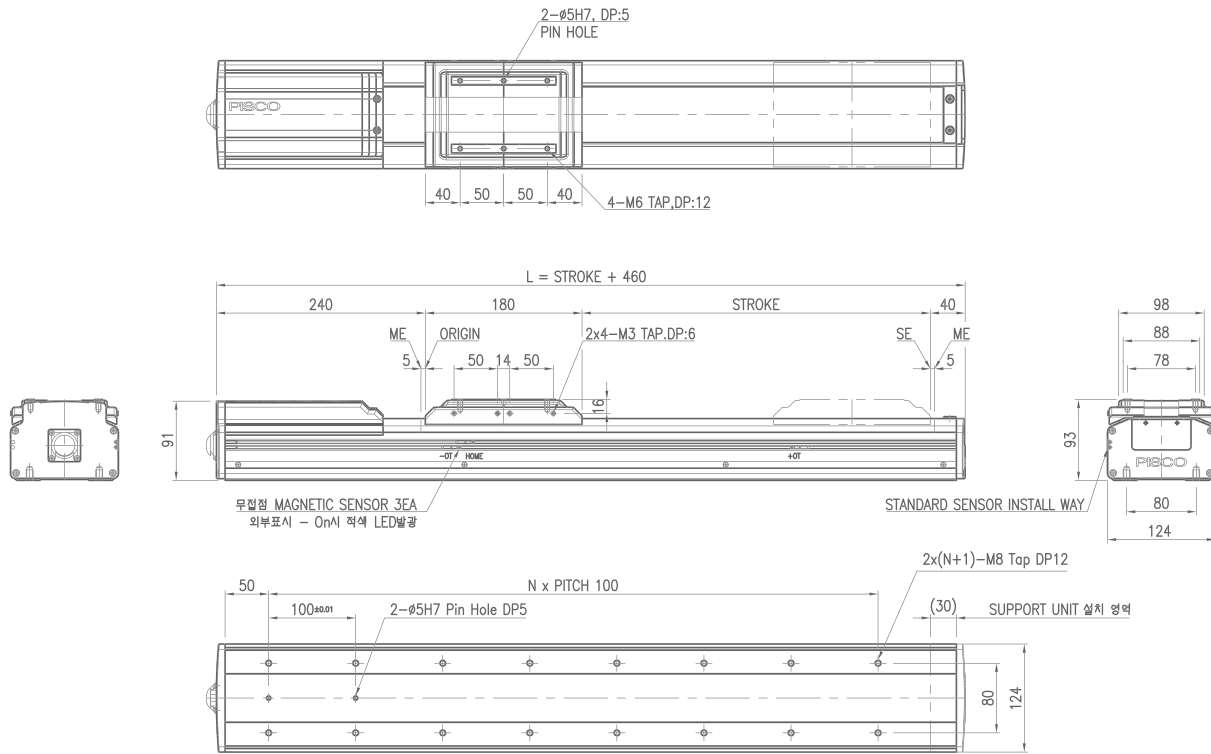
수평이송 Horizontal



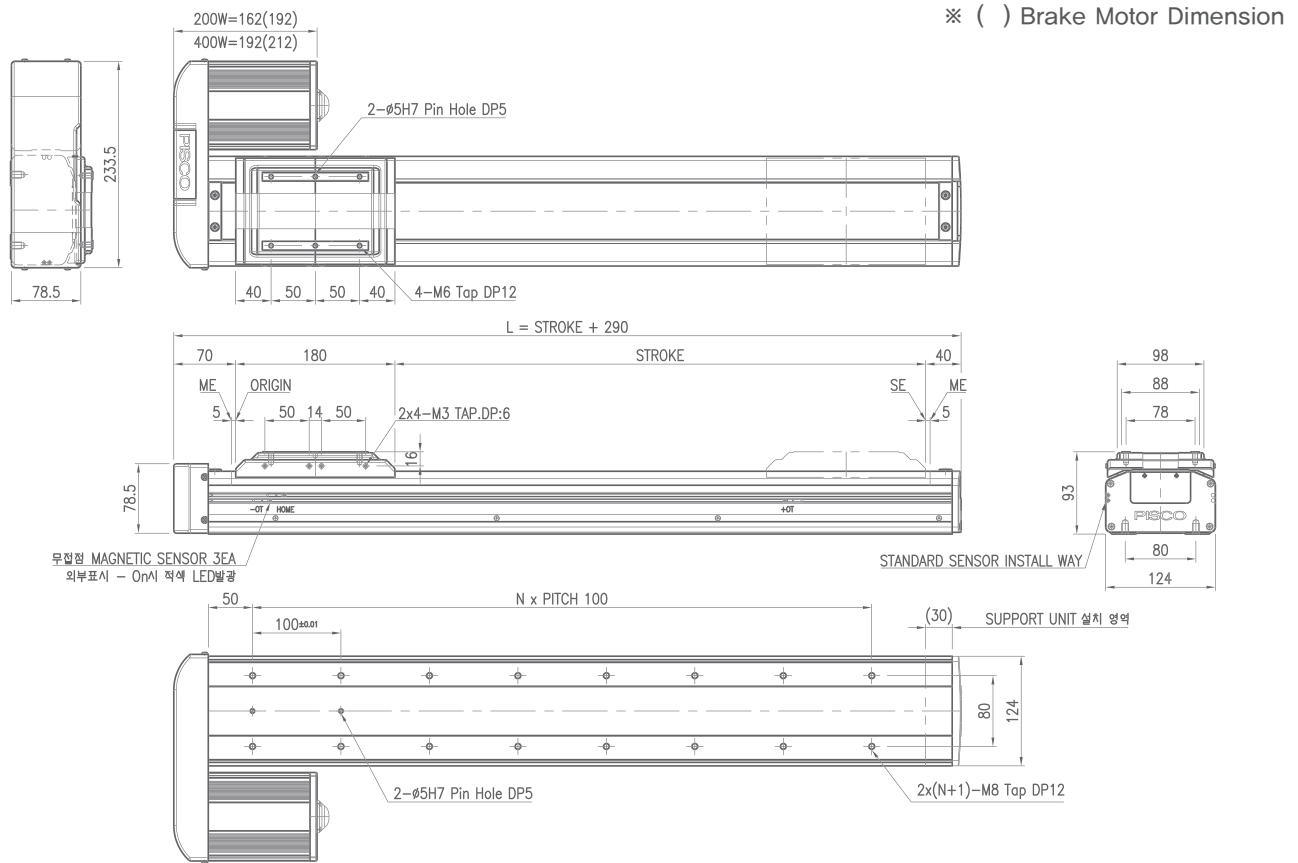
수직이송 Vertical



PHRC120-S-20(40)



PHRC120-L-20(40)



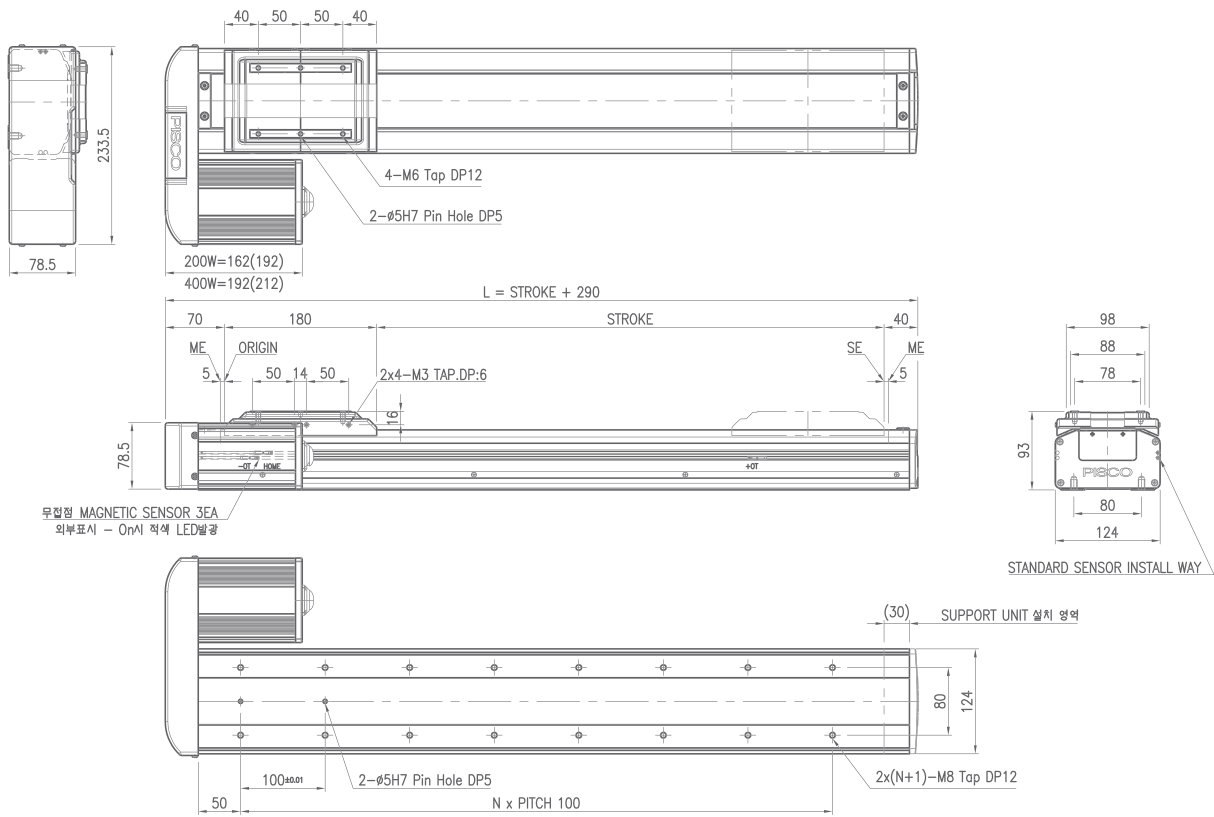
Clean Robot
Ball Screw Type

PHRC

치수도 Dimension (mm)

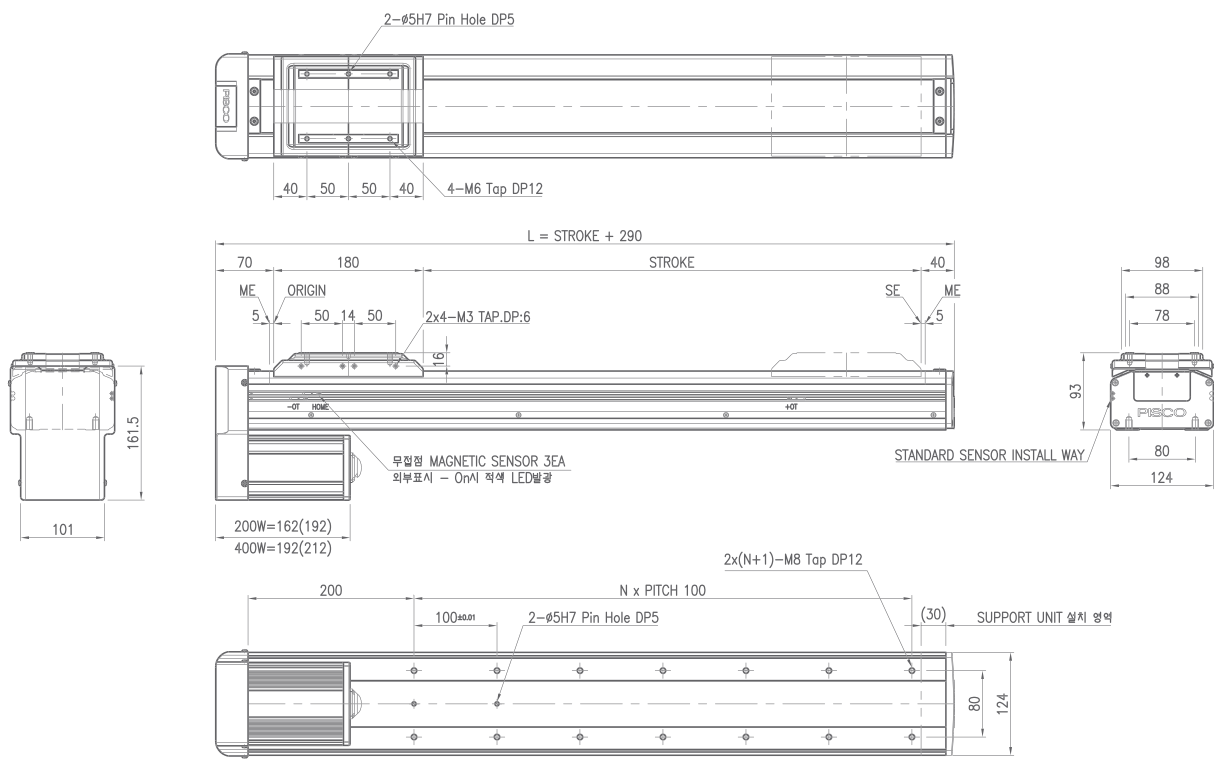
PHRC120-R-20(40)

※ () Brake Motor Dimension



PHRC120-U-20(40)

※ () Brake Motor Dimension



Clean Robot
Ball Screw Type

PHRC

PHRC Series

주문형식 Order Information



① 형식 Type

C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

160 160mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	1000	1500	2000	2500
L : 1505-C7		1000			
N : 1510-C7		1000			
H : 1520-C7		1000	1500		
P : 1530-C7		1000	1500		
L : 2005-C7		1000	1500		
N : 2010-C7		1000	1500		
H : 2020-C7		1000	1500	2000	
P : 2030-C7		1000	1500	2000	
S : 2040-C7		1000	1500	2000	
U : 2060-C5(*)		1000	1500	2000	

* 볼나사 규격 2060의 경우 특주로 대응됩니다.

⑤ 모터용량 Motor capacity

20 200W **40** 400W **75** 750W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s **H** 1000mm/s
P 1500mm/s **S** 2000mm/s **U(*2)** 3000mm/s

*1 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

*2 상기 사양은 특수사양으로 피스코코리아 모션사업부에 문의하여 주십시오.

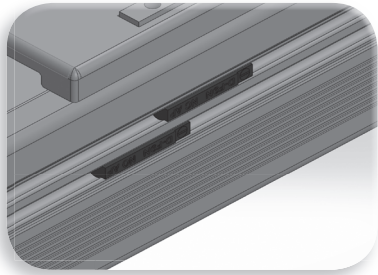
선택사양 Option



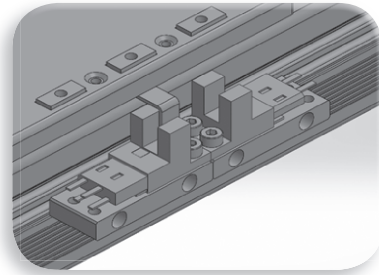
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment	
R1	LM Rail-Raydent	S1 Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2 Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent	
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent	

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot
Ball Screw Type

PHRC

사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 2200
Positioning Repeatability		±0.02 (Ground C7), ±0.01 (Ground C5)
Drive System	mm	Ball Screw Ø15, Ø20
Guide		2 Way 20W – 2UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Main & Side Cover		Steel Band & Aluminum Profile, Soft White Anodizing(※)
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

※ Side Cover에 Transparent PC Extrude Profile의 사양은 특주로 대응됩니다.

허용 이격 거리 Allowable Overhang Distance

Installation Types	Load capacity	Setting Angle	Allowable Overhang Distance (mm)			
			40kg	50kg	60kg	70kg
Horizontal Use		0°	340	280	235	205
		45°	280	226	191	166
		90°	1000	820	670	560
Wall Mount Use		0°	585	430	320	240
		45°	176	124	88	60
		90°	220	155	105	75
Vertical Use		0°	130	95	70	55
		45°	48	56	42	32
		90°	190	140	105	80
Estimated Condition	Stroke : 1000mm Speed : 1000mm/sec Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 400W		AC Servo Motor 750W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
1505-C7	L	250	70kg	70kg	70kg	70kg
1510-C7	N	500	70kg	44kg	70kg	70kg
1520-C7	H	1000	53kg	19kg	70kg	41kg
1530-C7	P	1500	21kg	11kg	66kg	25kg
2005-C7	L	250	70kg	46kg	70kg	70kg
2010-C7	N	500	70kg	44kg	70kg	70kg
2020-C7	H	1000	47kg	19kg	70kg	41kg
2030-C7	P	1500	18kg	11kg	63kg	25kg
2040-C7	S	2000	8kg	7kg	30kg	18kg
2060-C5(※)	U	3000	-	-	2kg	2kg
Estimated Condition	Stroke : 500mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

※ 볼나사 규격 2060의 경우 특주로 대응됩니다.

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)																									
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	
Ø15	5	250					215	172	141	117	99	85	74														
	10	500					430	344	281	234	198	170	147														
	20	1000					860	688	562	468	396	339	294	257	227	202	180	162									
	30	1500					1290	1032	844	703	594	509	441	386	341	303	271	244									
Ø20	5	250					242	198	165	140	120	104	91	80	71	64	57										
	10	500					485	396	330	279	239	207	181	160	142	127	115										
	20	1000					969	793	660	559	479	415	363	320	284	254	229	207	188	172	157	145					
	30	1500					1454	1189	991	838	718	622	544	480	427	382	344	311	282	258	236	217					
	40	2000					1939	1585	1321	1117	957	829	725	640	569	509	458	414	376	343	315	289					
	60(※)	3000					2908	2378	1981	1676	1436	1244	1088	960	853	763	687	621	564	515							

※ 볼나사 규격 2060의 경우 특주로 대응됩니다.

이송거리별 무게 Weight by Stroke

PHRC160 Robot			Stroke (mm) & Weight (kg)																									
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	
400W	Ø15	S	13.3	14.5	15.7	17.0	18.2	19.5	20.7	21.9	23.2	24.4	25.7	26.9	28.1	29.4	30.6	31.9	33.1									
		P	12.6	13.9	15.1	16.4	17.6	18.8	20.1	21.3	22.5	23.8	25.0	26.2	27.5	28.7	29.9	31.2	32.4									
	Ø20	S	14.3	15.7	17.1	18.5	19.8	21.2	22.6	24.0	25.4	26.8	28.2	29.5	30.9	32.3	33.7	35.1	36.5	37.9	39.3	40.6	42.0	43.4				
		P	13.7	15.1	16.5	17.9	19.3	20.7	22.1	23.5	24.9	26.3	27.6	29.0	30.4	31.8	33.2	34.6	36.0	37.4	38.8	40.2	41.5	42.9				
750W	Ø15	S	14.7	15.9	17.2	18.4	19.6	20.9	22.1	23.3	24.6	25.8	27.1	28.3	29.5	30.8	32.0	33.3	34.5									
		P	14.1	15.3	16.5	17.8	19.0	20.3	21.5	22.7	24.0	25.2	26.4	27.7	28.9	30.2	31.4	32.6	33.9									
	Ø20	S	15.7	17.1	18.5	19.9	21.3	22.7	24.0	25.4	26.8	28.2	29.6	31.0	32.4	33.8	35.1	36.5	37.9	39.3	40.7	42.1	43.5	44.8				
		P	15.2	16.6	18.0	19.3	20.7	22.1	23.5	24.9	26.3	27.7	29.0	30.4	31.8	33.2	34.6	36.0	37.4	38.8	40.1	41.5	42.9	44.3				

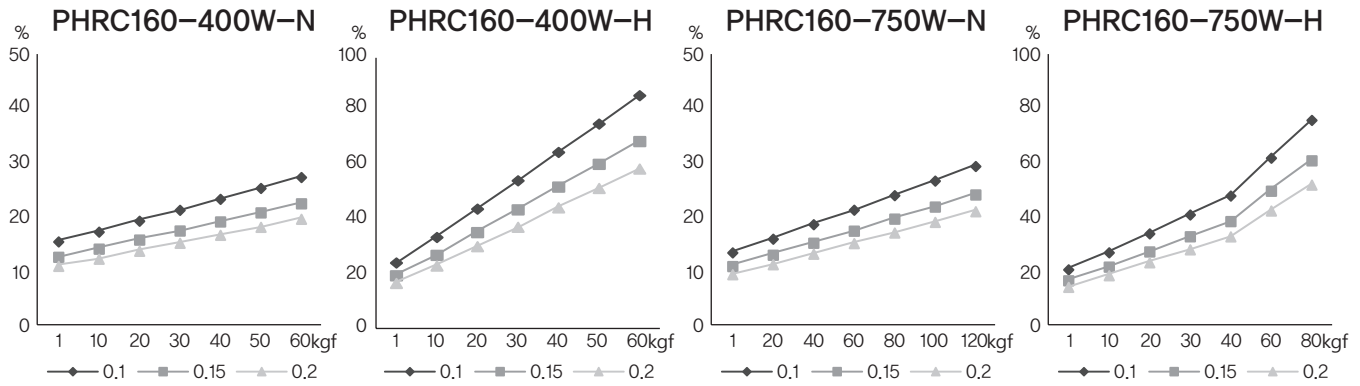
Clean Robot
Ball Screw Type

PHRC

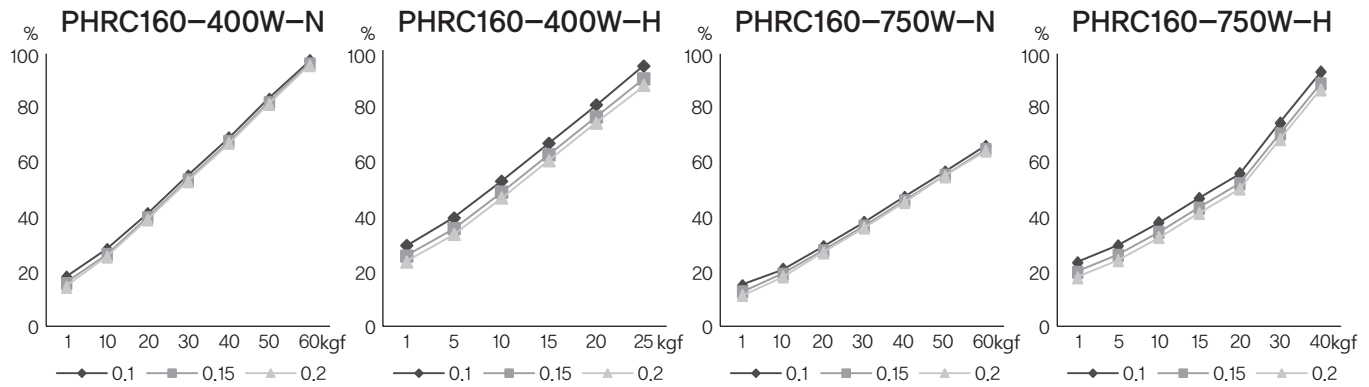
사양 Specifications

가속시간별 부하율표 Accelerating Time & Pay Load

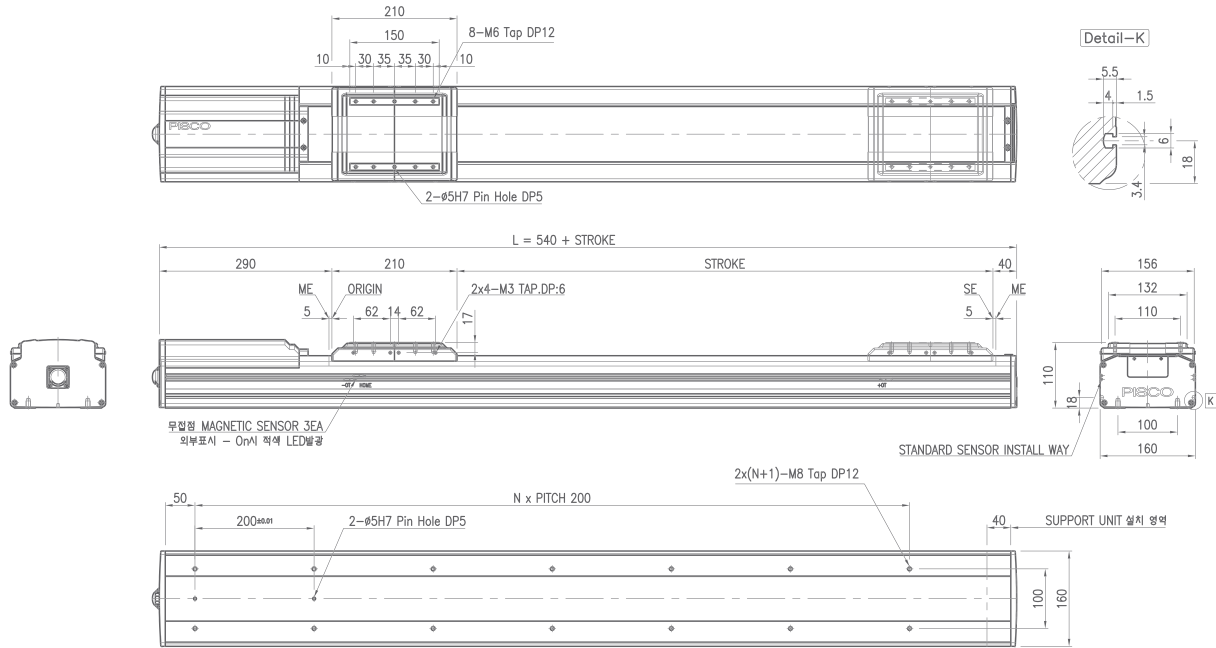
수평이송 Horizontal



수직이송 Vertical



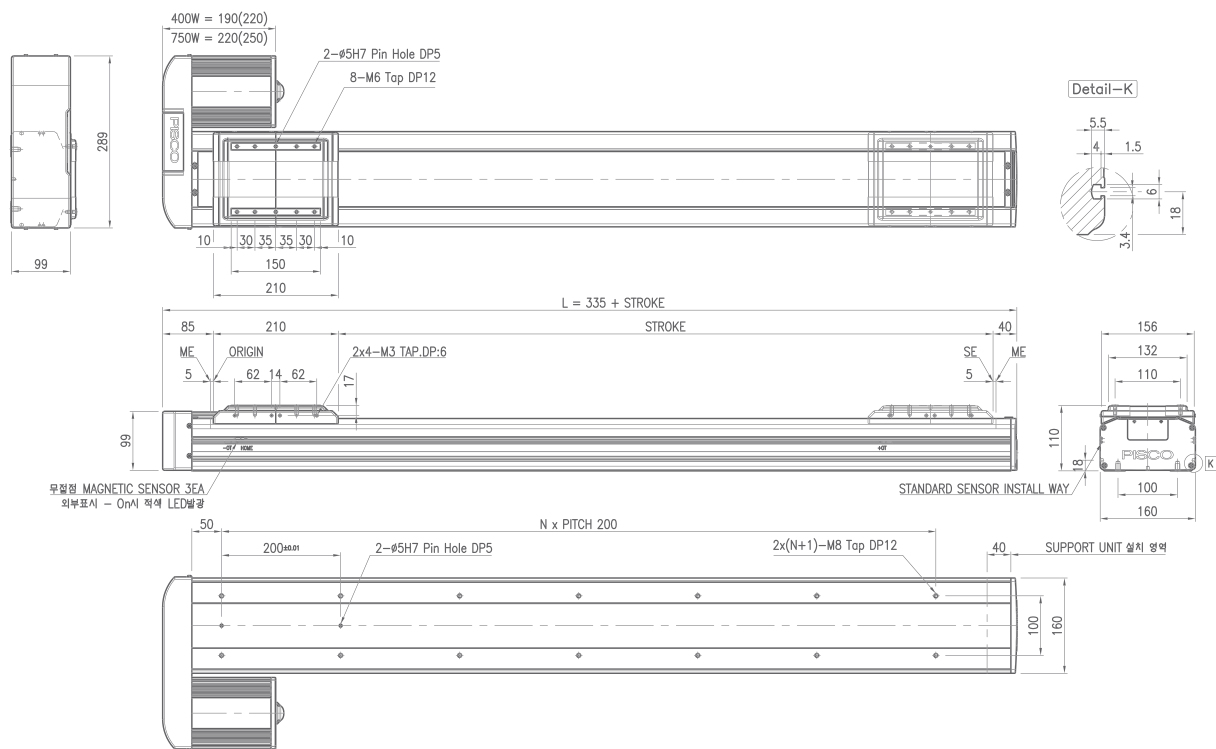
PHRC160-S-40(75)



Clean Robot Ball Screw Type
PHRC

PHRC160-L-40(75)

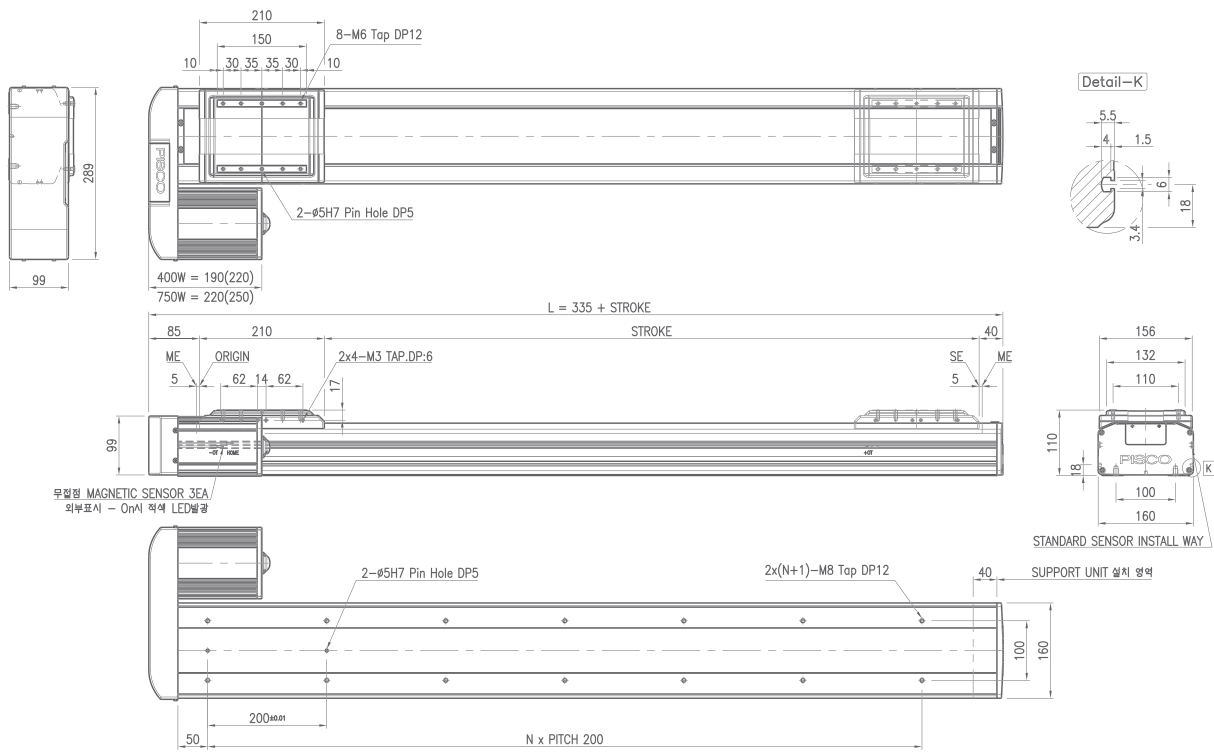
※ () Brake Motor Dimension



치수도 Dimension (mm)

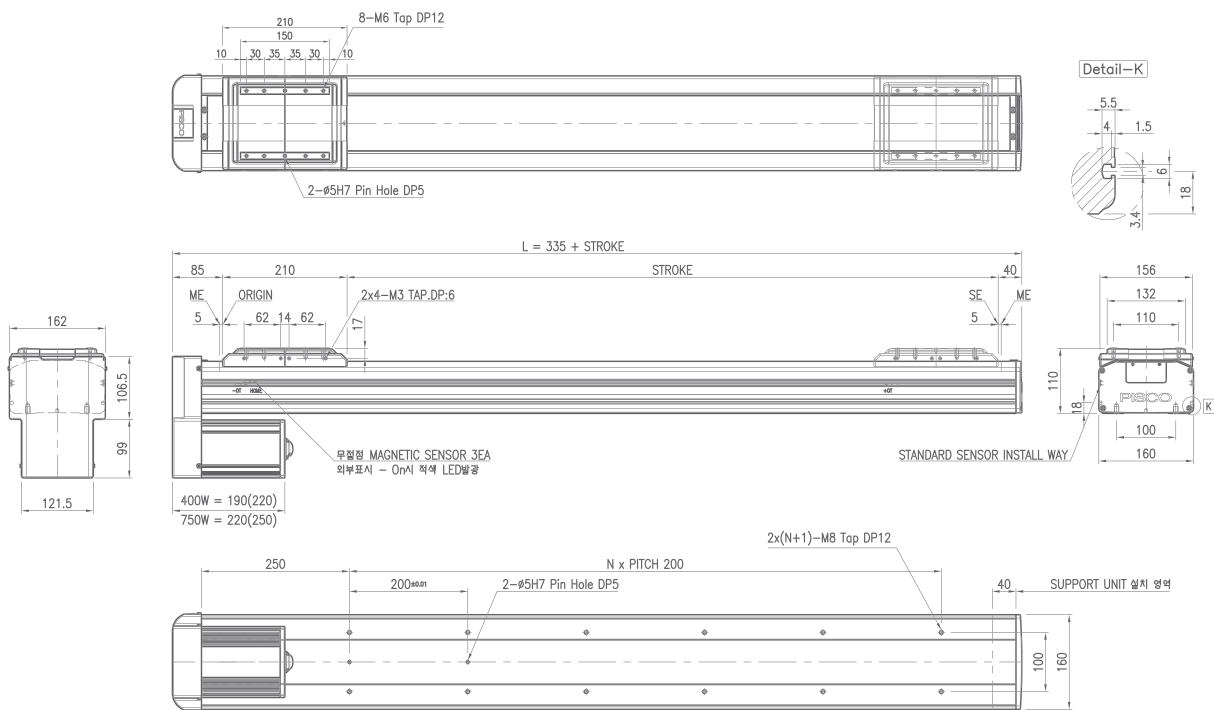
PHRC160-R-40(75)

※ () Brake Motor Dimension



PHRC160-U-40(75)

※ () Brake Motor Dimension



Clean Robot
Ball Screw Type

PHRC

PHRC Series

주문형식 Order Information



① 형식 Type

C Clean Robot, Ball Screw Type

② 본체 사이즈 Body Size

200 200mm

③ 형상 Shape

Normal Type



④ 이송거리 Stroke, In increment of 50mm

볼나사 규격	ST (mm)	1000	1500	2000	2500
L : 2005-C7		1000	1500		
N : 2010-C7		1000	1500		
H : 2020-C7		1000	1500	2000	
P : 2030-C7		1000	1500	2000	
S : 2040-C7		1000	1500	2000	
U : 2060-C5(※)		1000	1500	2000	
L : 2505-C7		1000	1500		
N : 2510-C7		1000	1500		
H : 2520-C7		1000	1500	2000	2500
P : 2530-C5(※)		1000	1500	2000	
U : 2550-C5(※)		1000	1500	2000	

※ 볼나사 규격 2060, 2530, 2550의 경우 특주로 대응됩니다.

⑤ 모터용량 Motor capacity

40 400W **75** 750W

⑥ 브레이크 부착 Motor Brake

None Without Brake **B** With Brake

⑦ 속도 Speed, Motor 3000 rpm

L 250mm/s **N** 500mm/s **H** 1000mm/s
P 1500mm/s **S** 2000mm/s **U** 3000mm/s

※ 볼나사의 회전수가 높아지면 축의 고유 진동수에 의한 공진 발생과 볼나사 축의 회전 원심력에 의한 내부 볼 순환 이상 및 리턴부 손상발생으로 위험속도를 계산하여 이송거리에 따른 최고 사용 속도를 정합니다.

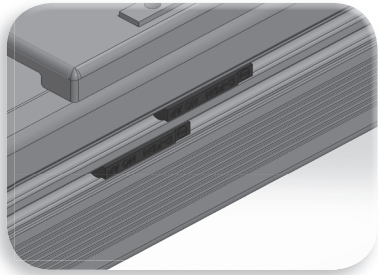
선택사양 Option



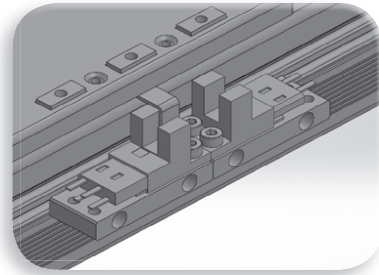
⑧ 로봇 색상 Robot Color Option

None	White (Standard)	B	Black Anodizing
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⑨ 센서 Sensor



None	External DC-24V Proximity LED Sensor (Standard)
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E1	SUNX (PM-Y54)
E2	OMRON (EE-SX674A)
E3	SUNX (PM-L24)

⑩ 표면처리 Surface Treatment

None	Without Surface Treatment	
R1	LM Rail-Raydent	S1 Screw Shaft-Raydent
R2	LM Rail+Block-Raydent	S2 Screw Shaft+Nut-Raydent
RS1	LM Rail & Screw Shaft-Raydent	
RS2	LM Rail+Block & Screw Shaft+Nut-Raydent	

⑪ 감속기 Reduction Gear

None	Without Reduction Gear (Standard)
G**	With Reduction Gear
**	Reduction Gear Ratio 03~10

⑫ 케이블베어 Cableveyor

None	Without Cableveyor	C	With Cableveyor
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Clean Robot
Ball Screw Type

PHRC

사양 Specifications

공통사양 Common Specifications

Stroke Range	mm	100 ~ 2500
Positioning Repeatability		±0.02 (Ground C7), ±0.01 (Ground C5)
Drive System	mm	Ball Screw Ø20, Ø25
Guide		2 Way 25W – 2UU
Main Base & Slide		Aluminum Profile, Soft White Anodizing
Main & Side Cover		Steel Band & Aluminum Profile, Soft White Anodizing(※)
Sensor Cable Length	mm	Standard Sensor Cable Body Out 300

※ Side Cover에 Transparent PC Extrude Profile의 사양은 특주로 대응됩니다.

허용 이격 거리 Allowable Overhang Distance

Installation Types Load capacity		Setting Angle	Allowable Overhang Distance (mm)			
			40kg	50kg	60kg	70kg
Horizontal Use		0°	450	350	280	240
		45°	353	268	219	183
		90°	800	800	630	500
Wall Mount Use		0°	730	510	370	270
		45°	261	176	127	92
		90°	340	220	150	100
Vertical Use		0°	165	115	85	65
		45°	100	71	50	40
		90°	220	150	110	85
Estimated Condition	Stroke : 1000mm Speed : 1000mm/sec Acceleration : 0.2sec Life in traveled distance : 15000km or 15000Hr					

최고속도 및 부하하중 Max Speed & Pay Load

Ball Screw Specifications	Max Speed		AC Servo Motor 400W		AC Servo Motor 750W	
	Mark	mm/s	Horizontal	Vertical	Horizontal	Vertical
2005-C7	L	250	120kg	90kg	120kg	120kg
2010-C7	N	500	120kg	40kg	120kg	83kg
2020-C7	H	1000	31kg	16kg	120kg	37kg
2030-C7	P	1500	9kg	8kg	55kg	22kg
2040-C7	S	2000	1kg	1kg	24kg	14kg
2060-C5(※)	U	3000	-	-	5kg	4kg
2505-C7	L	250	120kg	90kg	120kg	120kg
2510-C7	N	500	86kg	40kg	120kg	83kg
2520-C7	H	1000	15kg	13kg	120kg	37kg
2530-C5(※)	P	1500	2kg	1kg	47kg	22kg
2550-C5(※)	U	2500	-	-	9kg	8kg
Estimated Condition	Stroke : 500mm Speed : Max Speed Acceleration : 0.2sec Servo Motor Rotate : 3000rpm					

※ 불나사 규격 2060, 2530, 2550의 경우 특주로 대응됩니다.

이송거리별 최고속도 Max Speed by Stroke

Ball Screw		Stroke (mm) & Speed (mm/sec)																								
DIA	Lead	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500
Ø20	5				250				227	187	156	133	114	99	87	77	69	61	55							
	10				500				454	373	313	266	228	199	174	154	137	123	111							
	20				1000				907	746	625	531	457	397	348	308	274	246	221	201	183	167	153	141		
	30				1500				1361	1120	938	797	685	596	522	462	411	369	332	301	274	251	230	212		
	40				2000				1814	1493	1250	1062	913	794	696	616	548	491	443	401	365	334	307	282		
	60(※)				3000				2721	2239	1875	1593	1370	1191	1044	924	822	737	664	602	548	501				
Ø25	5				250				242	202	172	148	128	113	100	89	80	72								
	10				500				484	405	344	296	257	225	199	177	159	143								
	20				1000				967	809	687	591	514	450	398	355	318	286	260	236	216	198	182	169	156	
	30(※)				1500				1451	1214	1031	887	771	676	598	532	477	430	390	355						
	50(※)				2500				2418	2023	1718	1478	1284	1126	996	887	795	716	649	591	540					

※ 볼나사 규격 2060, 2530, 2550의 경우 특주로 대응됩니다.

이송거리별 무게 Weight by Stroke

PHRC200 Robot			Stroke (mm) & Weight (kg)																								
Motor	DIA	Type	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500
400W	Ø20	S	25.5	27.9	30.2	32.6	35.0	37.3	39.7	42.1	44.5	46.8	49.2	51.6	53.9	56.3	58.7	61.0	63.4	65.8	68.1	70.5	72.9	75.2	77.6		
		P	22.8	25.1	27.5	29.9	32.3	34.6	37.0	39.4	41.7	44.1	46.5	48.8	51.2	53.6	56.0	58.3	60.7	63.1	65.4	67.8	70.2	72.5	74.9		
	Ø25	S	26.4	28.9	31.3	33.8	36.3	38.8	41.2	43.7	46.2	48.6	51.1	53.6	56.0	58.5	61.0	63.5	65.9	68.4	70.9	73.3	75.8	78.3	80.7	83.2	85.7
		P	23.5	25.9	28.4	30.9	33.3	35.8	38.3	40.8	43.2	45.7	48.2	50.6	53.1	55.6	58.0	60.5	63.0	65.5	67.9	70.4	72.9	75.3	77.8	80.3	82.7
750W	Ø20	S	26.9	29.3	31.7	34.0	36.4	38.8	41.2	43.5	45.9	48.3	50.6	53.0	55.4	57.7	60.1	62.5	64.9	67.2	69.6	72.0	74.3	76.7	79.1		
		P	24.3	26.7	29.0	31.4	33.8	36.1	38.5	40.9	43.2	45.6	48.0	50.3	52.7	55.1	57.4	59.8	62.2	64.5	66.9	69.3	71.6	74.0	76.4		
	Ø25	S	27.8	30.3	32.8	35.2	37.7	40.2	42.7	45.1	47.6	50.1	52.5	55.0	57.5	59.9	62.4	64.9	67.4	69.8	72.3	74.8	77.2	79.7	82.2	84.6	87.1
		P	25.0	27.4	29.9	32.4	34.8	37.3	39.8	42.3	44.7	47.2	49.7	52.1	54.6	57.1	59.5	62.0	64.5	67.0	69.4	71.9	74.4	76.8	79.3	81.8	84.2

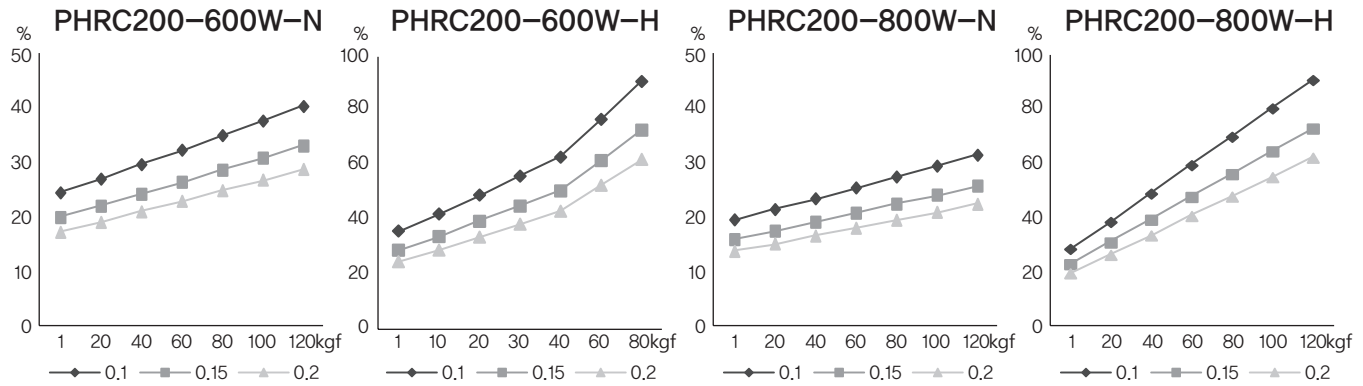
Clean Robot
Ball Screw Type

PHRC

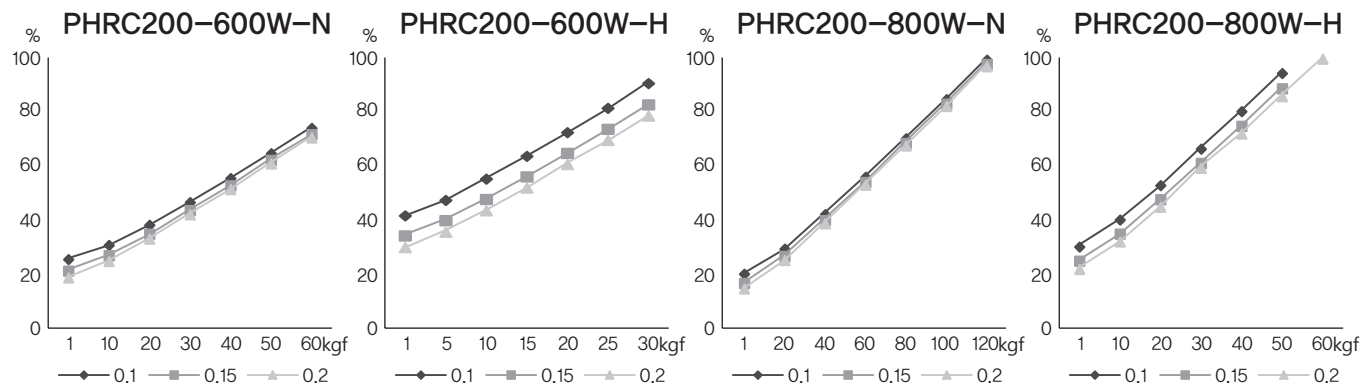
사양 Specifications

가속시간별 부하율표 Accelerating Time & Pay Load

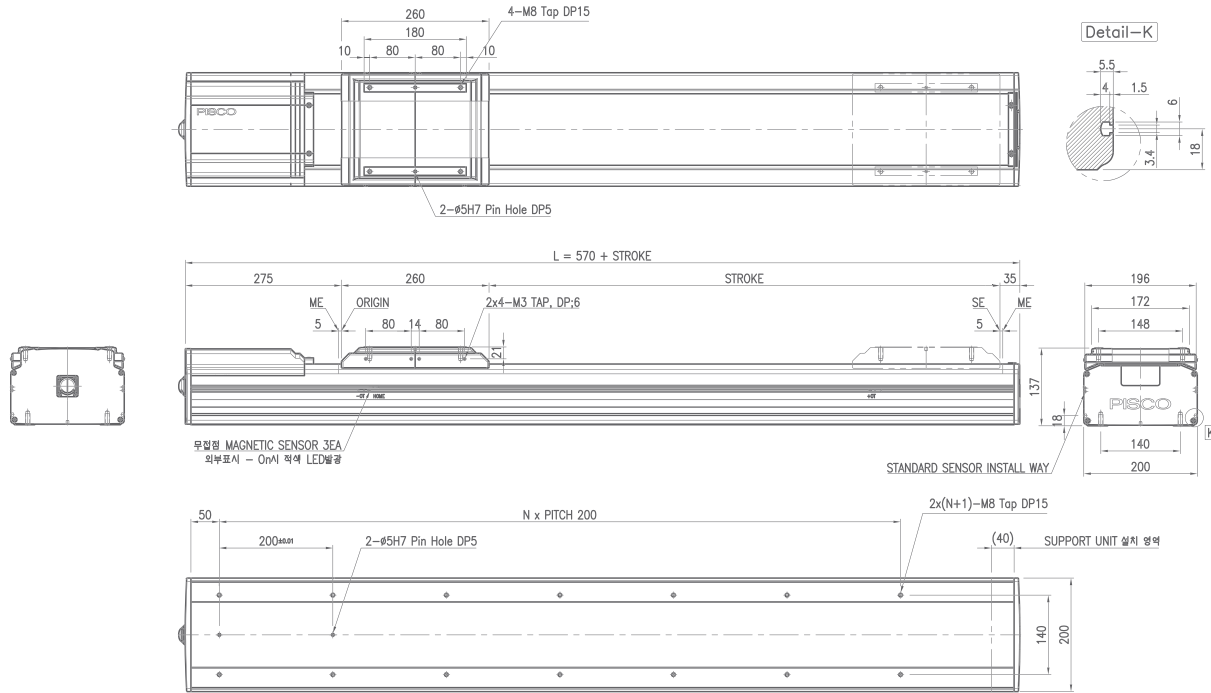
수평이송 Horizontal



수직이송 Vertical



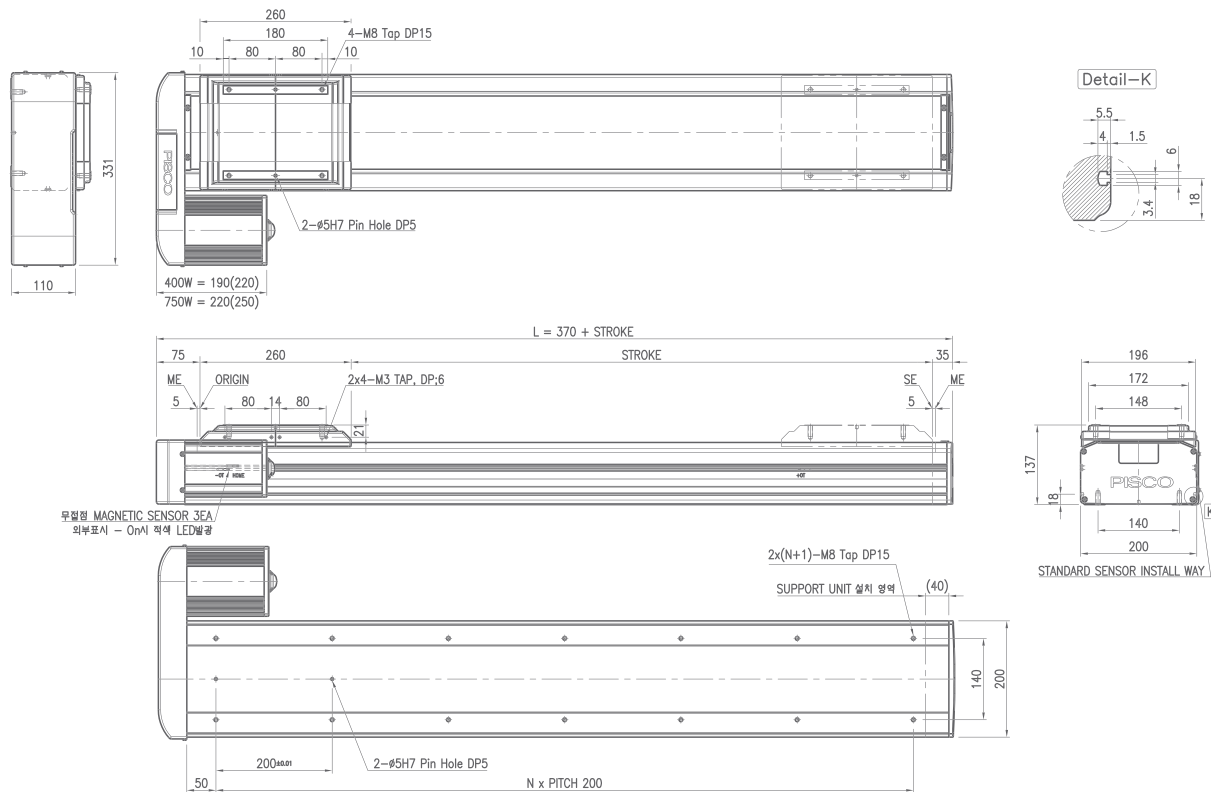
PHRC200-S-40(75)



Clean Robot
Ball Screw Type
PHRC

PHRC200-L-40(75)

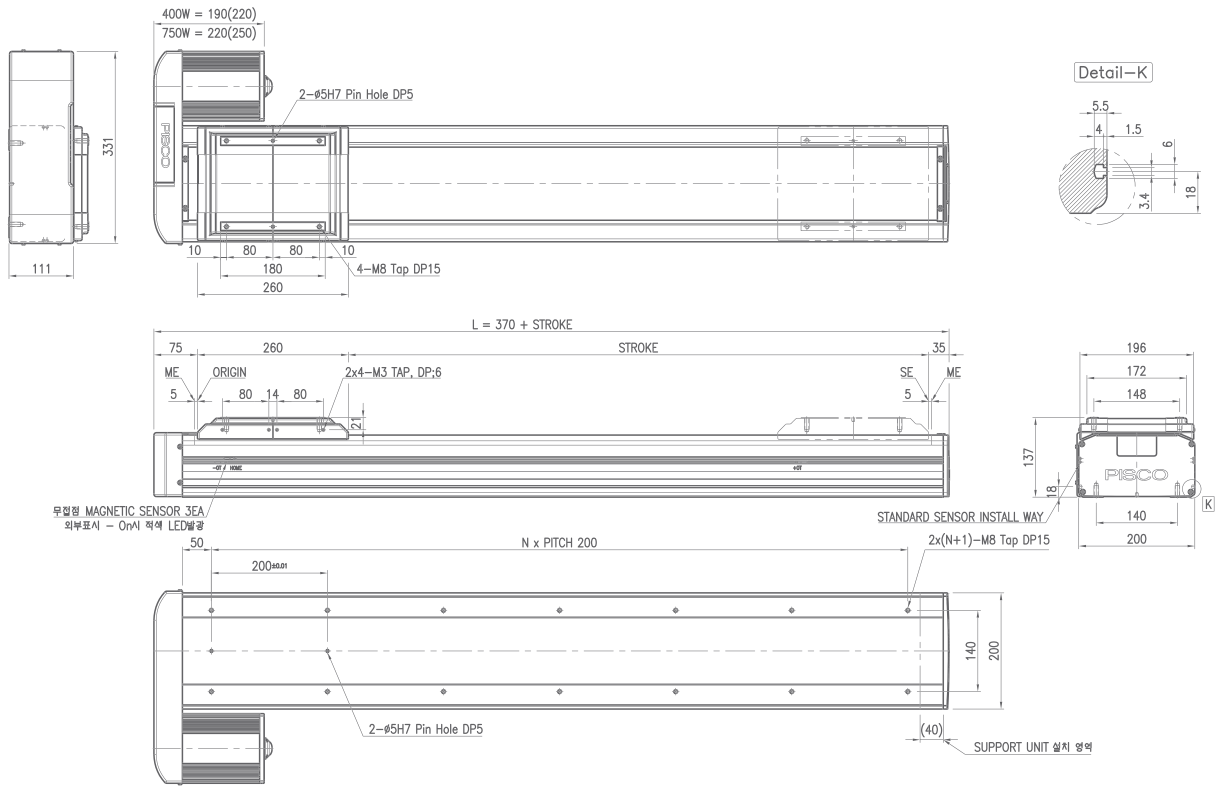
※ () Brake Motor Dimension



치수도 Dimension (mm)

PHRC200-R-40(75)

※ () Brake Motor Dimension



PHRC200-U-40(75)

※ () Brake Motor Dimension

